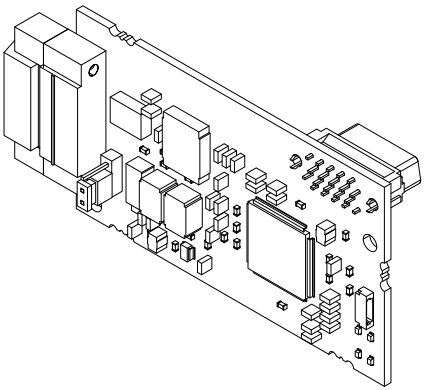
YASKAWA

YASKAWA AC Drive Option

CC-Link
Installation Manual

Model SI-C3

To properly use the product, read this manual thoroughly and retain for easy reference, inspection, and maintenance. Please keep this manual in your possession and ensure that it is delivered to the end user.



MANUAL NO. TOEP C730600 83A

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1 Preface and Safety

YASKAWA Electric supplies component parts for use in a wide variety of industrial applications. The selection and application of YASKAWA products remain the responsibility of the equipment designer or end user.

YASKAWA accepts no responsibility for the way its products are incorporated into the final system design. Under no circumstances should any YASKAWA product be incorporated into any product or design as the exclusive or sole safety control. Without exception, all controls should be designed to detect faults dynamically and fail safely under all circumstances. All products designed to incorporate a component part manufactured by YASKAWA must be supplied to the end user with appropriate warnings and instructions as to the safe use and operation of that part. Any warnings provided by YASKAWA must be promptly provided to the end user. YASKAWA offers an express warranty only as to the quality of its products in conforming to standards and specifications published in the manual. NO OTHER WARRANTY, EXPRESS OR IMPLIED, IS OFFERED. YASKAWA assumes no liability for any personal injury, property damage, losses, or claims arising from misapplication of its products.

◆ Applicable Documentation

Document	Description
YASKAWA AC Drive Option CC-Link Installation Manual (This book)	Read this manual first. The manual provides information about wiring, settings, functions, and troubleshooting. The manual is packaged together with the product.
YASKAWA AC Drive Option CC-Link Technical Manual MANUAL NO. SIEP C730600 83	The technical manual contains detailed information about the option. Access the following sites to obtain the technical manual: U.S.: http://www.yaskawa.com Europe: http://www.yaskawa.eu.com Japan: http://www.e-mechatronics.com Other areas: Check the back cover of these manuals. For questions, contact Yaskawa or a Yaskawa representative.
YASKAWA AC Drive Manuals	Refer to the drive manual to connect with the option. Drive manuals contain basic installation and wiring information in addition to detailed parameter setting, fault diagnostic, and maintenance information. The manuals also include important information about parameter settings and tuning the drive. The Quick Start Guides are packaged with the drive. The most recent versions of these manuals are available for download on our documentation websites: U.S.: http://www.yaskawa.com Europe: http://www.yaskawa.eu.com Japan: http://www.e-mechatronics.com Other areas: Check the back cover of these manuals. For questions, contact Yaskawa or a Yaskawa representative.

◆ Glossary

Terms	Definition
Option	YASKAWA AC Drive Option SI-C3 CC-Link
Keypad	• HOA Operator • LCD Operator • LED Operator • HOA Keypad • LCD Keypad • LED Keypad
Hex. (Example: 900 (Hex.))	Identifies a unit for hexadecimal number format.

◆ Registered Trademarks

- CC-Link is a registered trademark of CC-Link Partner Association.
- Trademarks are the property of their respective owners.

◆ Supplemental Safety Information

Read and understand this manual before installing, operating, or servicing this option. The option must be installed according to this manual and local codes.

The following conventions are used to indicate safety messages in this manual. Failure to heed these messages could result in serious or possibly even fatal injury or damage to the products or to related equipment and systems.

⚠ DANGER *This signal word identifies a hazard that will cause serious injury or death if you do not prevent it.*

⚠ WARNING *This signal word identifies a hazard that can cause death or serious injuries if you do not prevent it.*

⚠ CAUTION *This signal word identifies a hazardous situation, which, if not avoided, can cause minor or moderate injury.*

NOTICE *This signal word identifies a property damage message that is not related to personal injury.*

■ Section Safety

General Precautions
• The diagrams in this section may include options and drives without covers or safety shields to illustrate details. Be sure to reinstall covers or shields before operating any devices. The option should be used according to the instructions described in this manual. • The diagrams in this manual are provided as examples only and may not pertain to all products covered by this manual. • The products and specifications described in this manual or the content and presentation of the manual may be changed without notice to improve the product and/or the manual. • Contact Yaskawa or a Yaskawa representative and provide the manual number shown on the front cover to order new copies of the manual.

⚠ DANGER *Do not ignore the safety messages in this manual. If you ignore the safety messages in this manual, it will cause serious injury or death. The manufacturer is not responsible for injuries or damage to equipment.*

⚠ WARNING *Electrical Shock Hazard. Do not modify the drive or option circuitry. Failure to obey can cause serious injury or death, or cause damage to the drive or option and will void warranty. Yaskawa is not responsible for modifications of the product made by the user.*

NOTICE *Damage to Equipment. Do not use steam or other disinfectants to fumigate wood for packaging the drive. Use alternative methods, for example heat treatment, before you package the components. Gas from wood packaging fumigated with halogen disinfectants, for example fluorine, chlorine, bromine, iodine or DOP gas (phthalic acid ester), can cause damage to the drive.*

2 Overview

This option is designed for connecting a drive to a field network using the CC-Link protocol. This option conforms to CC-Link Ver.1.10.

Install the option/CC-Link option on a drive to perform the following functions from a CC-Link master device:

- Operate the drive
- Monitor the drive operation status
- Change drive parameter settings

Figure 2.1 CC-Link Approved

◆ Compatible Products

You can use the option with these products:

Table 2.1 Compatible Products

Drive	Model	Software version *1
A1000	CIMR-AxxAxxxx	≥ 1020
D1000 *2	CIMR-DxxAxxxx	≥ 2005 (≥ 3013 for a 400 V class 630 kW unit)
U1000	CIMR-UxxAxxxx	≥ 1010
	CIMR-UxxExxxx	
	CIMR-UxxPxxxx	
	CIMR-UxxWxxxx	
Z1000U	CIMR-ZxxAxxxx	≥ 6110
	CIMR-ZxxExxxx	
	CIMR-ZxxPxxxx	
	CIMR-ZxxWxxxx	
GA500	CIPR-GA50xxxxx	≥ 1010
GA700	CIPR-GA70xxxxx	≥ 1010
GA800	CIPR-GA80xxxxx	≥ 9010

*1 Refer to “PRG” on the drive nameplate for the software version number.
*2 Before you install the option on a YASKAWA Energy-Saving Unit D1000, make sure that the option software version is PRG: 0106 or later.

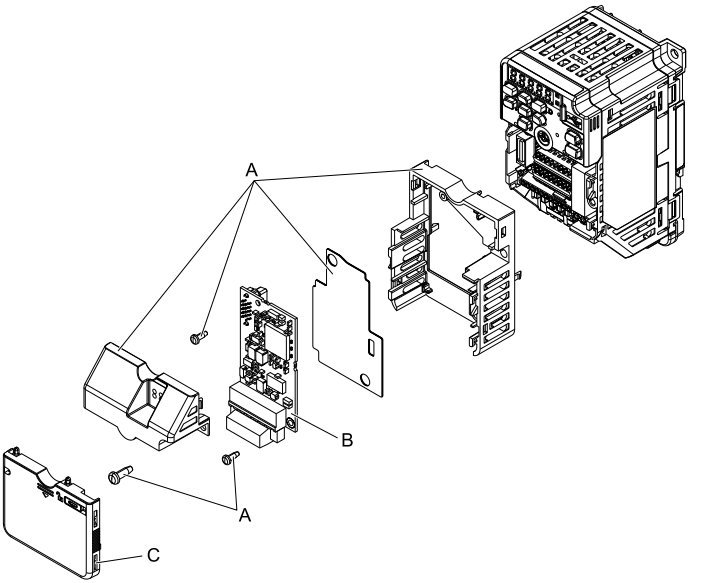
Note:

Refer to the option package labeling in the field designated “PRG (four digit number)” or the option labeling in the field designated “C/N (S + four digit number)” to identify the option software version.

◆ Install the Option on a GA500 Drive

An option card mounting kit is necessary to install the option on a GA500 drive. The option card mounting kit model is: JOHB-GA50. This kit is sold separately.

Refer to the option card mounting kit manual for more information about installation.



A - Option card mounting kit components (sold separately)

B - Option

C - Drive front cover

Figure 2.2 Option Card Mounting Kit (JOHB-GA50)

3 Receiving

After you receive the option package, check these items.

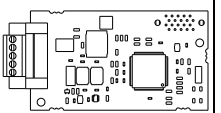
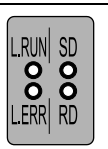
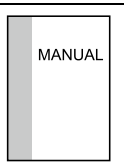
- Make sure that there is no damage to the option and no parts are missing.
  The Yaskawa warranty does not cover damage from shipping. Immediately contact the shipping company if there is damage to the option.

NOTICE *Damage to Equipment. Do not use damaged parts to connect the drive and the option. Failure to comply could damage the drive and option.*

- Make sure that the model number on the option nameplate and the model number on the purchase order are the same. Refer to Figure 4.1 for print location.
- Contact the distributor where you purchased the option or contact Yaskawa or a Yaskawa representative about any problems with the option.

◆ Option Package Contents

Table 3.1 Contents of Package

Option Contents			Quantity
Option			1
Ground wire *1			1
Screws (M3)			3 *2
LED Labels	1000-Series		1
	GA500, GA700, GA800		1
Manuals			1

*1 GA700 and GA800 drives do not use the ground wire.
*2 Only two screws are necessary to install the option on GA700 and GA800 drives.

◆ Installation Tools

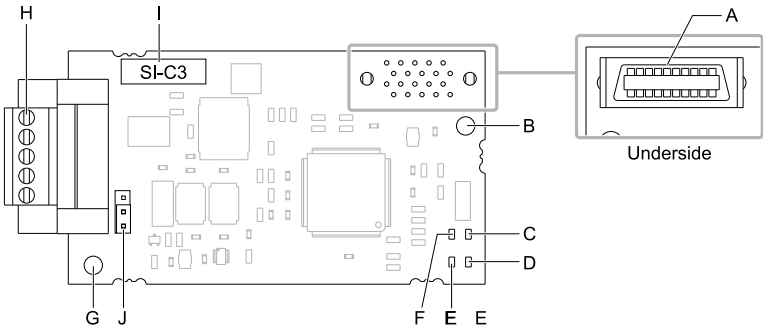
You can use these tools to install the option to the drive:

- Phillips screwdriver or slotted screwdriver *1
- A flat-blade screwdriver (blade depth: 0.4 mm (0.02 in.), width: 2.5 mm (0.1 in.)).
- A pair of diagonal cutting pliers.
- A small file or medium-grit sandpaper.

*1 Phillips screw sizes are different for different drive capacities. Prepare different screwdrivers for different screw sizes.

4 Option Components

◆ Option



A - Connector (CN5)
B - Installation hole
C - LED (L.RUN) **1*
D - LED (SD) **1*
E - LED (RD) **1*
F - LED (L.ERR) **1*
G - Ground terminal (FE) and installation hole **2*
H - Communication connector CN1
I - Option model number
J - Grounding method switch (S1) **3*

Figure 4.1 Option

*1 Refer to *Option LED Display on page 15* and *Option LED States on page 57* for more information about the LEDs.
*2 Connect the included ground wire during installation. The ground wire is not necessary for installations on GA700 and GA800 drives.
*3 The board code is available only for ETC740051 and later. Check the board code printed on the back of your option.

◆ Option Modular Connector

Table 4.1 Option Terminal Descriptions

Terminal No.	Name	Description
1	DA	Communication Data +
2	DB	Communication Data –
3	DG	Signal Ground

Terminal No.	Name	Description
4	SLD	Shield
5	SLD	Shield

Figure 4.2 Option Modular Connector (CN1)

◆ Option LED Display

A

B

A - 1000-Series **B - GA500, GA700, GA800**

Figure 4.3 Option LED Labels

Table 4.2 Option LED Display

LED Name	Indication		Operating State	Description
	Color	Display		
L.RUN	Green	ON	Normal operation	Receiving data normally
		OFF	Timed out	• Timed out waiting to receive • Logging onto the network • During reset
L.ERR	Red	ON	CRC error	• CRC error • Station address setting error (*F6-10 = 0 [CC-Link Node Address = 0]*)
		OFF	During communications	• Normal communications • During reset
SD	Red	ON	Sending data	Sending data **Note:** LED may appear to flash with slower baud rates.
		OFF	No data transfer	• No data being sent • During reset
RD	Red	ON	Detecting data received	Detecting data that was received **Note:** LED may appear to flash with slower baud rates.
		OFF	Waiting for data	• Data not yet received • During reset

◆ Setting Station Address

Set *F6-10 [CC-Link Node Address]* to a station address (Range *1* to *64*) unique to the network. If you set *F6-10 = 0*, the L.ERR light will turn ON and an *AEr [Station Address Setting Error]* will occur.

5 Installation Procedure

◆ Section Safety

⚠ DANGER *Electrical Shock Hazard. Do not examine, connect, or disconnect wiring on an energized drive. Before servicing, disconnect all power to the equipment and wait for the time specified on the warning label at a minimum. The internal capacitor stays charged after the drive is de-energized. The charge indicator LED extinguishes when the DC bus voltage decreases below 50 Vdc. When all indicators are OFF, measure for dangerous voltages to make sure that the drive is safe. If you do work on the drive when it is energized, it will cause serious injury or death from electrical shock.*

⚠ WARNING *Electrical Shock Hazard. Do not operate the drive when covers are missing. Replace covers and shields before you operate the drive. Use the drive only as specified by the instructions. Some figures in this section include drives without covers or safety shields to more clearly show the inside of the drive. If covers or safety shields are missing from the drive, it can cause serious injury or death.*

⚠ WARNING *Electrical Shock Hazard. Only let approved personnel install, wire, maintain, examine, replace parts, and repair the drive. If personnel are not approved, it can cause serious injury or death.*

⚠ WARNING *Electrical Shock Hazard. Do not remove covers or touch circuit boards while the drive is energized. If you touch the internal components of an energized drive, it can cause serious injury or death.*

⚠ WARNING *Electrical Shock Hazard. Do not use damaged wires, put too much force on the wiring, or cause damage to the wire insulation. Damaged wires can cause serious injury or death.*

⚠ WARNING *Fire Hazard. Tighten all terminal screws to the correct tightening torque. Connections that are too loose or too tight can cause incorrect operation and damage to the drive. Incorrect connections can also cause death or serious injury from fire.*

NOTICE *Damage to Equipment. When you touch the option, make sure that you observe correct electrostatic discharge (ESD) procedures. If you do not follow procedures, it can cause ESD damage to the drive circuitry.*

NOTICE *Damage to Equipment. Do not de-energize the drive while the drive is outputting voltage. Incorrect equipment sequencing can cause damage to the drive.*

NOTICE *Do not operate a drive or connected equipment that has damaged or missing parts. You can cause damage to the drive and connected equipment.*

NOTICE *Use Yaskawa connection cables or recommended cables only. Incorrect cables can cause the drive or option to function incorrectly.*

NOTICE *Damage to Equipment. Correctly connect the connectors. Incorrect connections can cause malfunction or damage to the equipment.*

NOTICE *Damage to Equipment. Make sure that all connections are correct after you install the drive and connecting peripheral devices. Incorrect connections can cause damage to the option.*

◆ Procedures to Install and Wire Options on a Drive

Procedures to install and wire the option are different for different drive models.

Refer to the following table to check the procedures to install and wire the option on a drive.

Table 5.1 Procedures to Install and Wire Options on a Drive

Drive	Procedures to Install and Wire Options on a Drive	Reference Page
A1000	Procedure A	17
D1000	Procedure A	17
U1000	Procedure A	17
Z1000U	Procedure A	17
GA500	*1	-
GA700	Procedure B	23
GA800	Procedure B	23

*1 To install the option on GA500 drives, use the option mounting kit (JOHB-GA50) and manual.

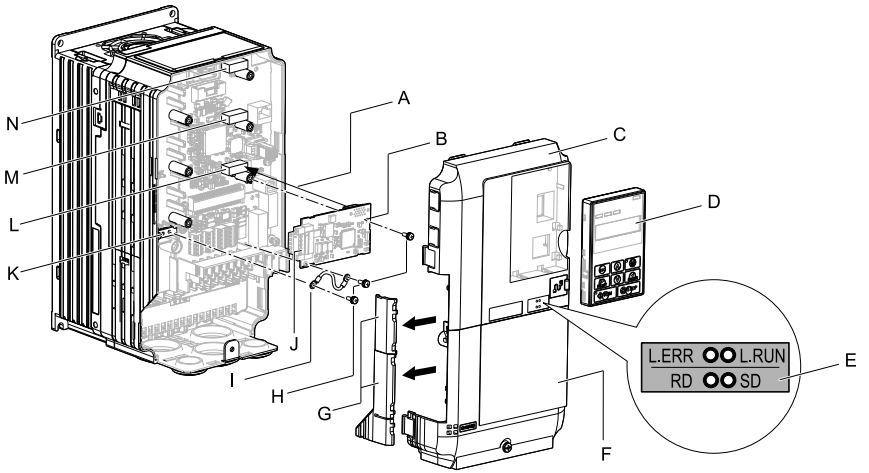
■ Procedure A

This section shows the procedure to install and wire the option on a 1000-series drive.

Prepare the Drive for the Option

Before you install the option on a YASKAWA Energy-Saving Unit D1000, make sure that the option software version is PRG: 0106 or later.

Correctly wire the drive as specified by the manual packaged with the drive. Make sure that the drive functions correctly. Refer to the drive manuals for more information.



A - Insertion point for CN5 connector
B - Option
C - Drive front cover
D - Keypad
E - LED label
F - Drive terminal cover
G - Removable tabs for wire routing
H - Included screws
I - Ground wire
J - Option modular connector CN1
K - Drive grounding terminal (FE)
L - Connector CN5-A
M - Connector CN5-B (Not available for communication option installation.)
N - Connector CN5-C (Not available for communication option installation.)

Figure 5.1 Drive Components with Option

Install the Option

Use this procedure to install the option.

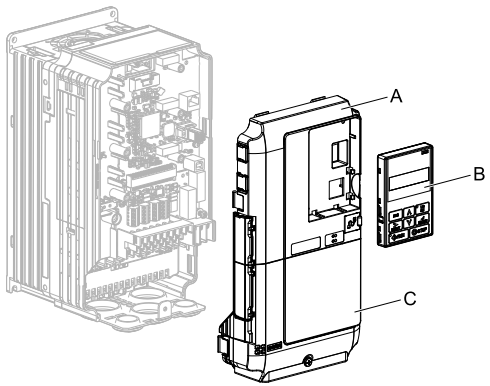
⚠ DANGER *Electrical Shock Hazard. Do not examine, connect, or disconnect wiring on an energized drive. Before servicing, disconnect all power to the equipment and wait for the time specified on the warning label at a minimum. The internal capacitor stays charged after the drive is de-energized. The charge indicator LED extinguishes when the DC bus voltage decreases below 50 Vdc. When all indicators are OFF, measure for dangerous voltages to make sure that the drive is safe. If you do work on the drive when it is energized, it will cause serious injury or death from electrical shock.*

1. Remove the keypad (B), front cover (A), and terminal cover (C).

   Shut off power to the drive and wait for the time specified on the drive warning label at a minimum. Make sure that the charge indicator LED is unlit, then remove the keypad and front cover. Refer to the drive manuals for more information.

You can only install this option into the CN5-A connector on the drive control board.

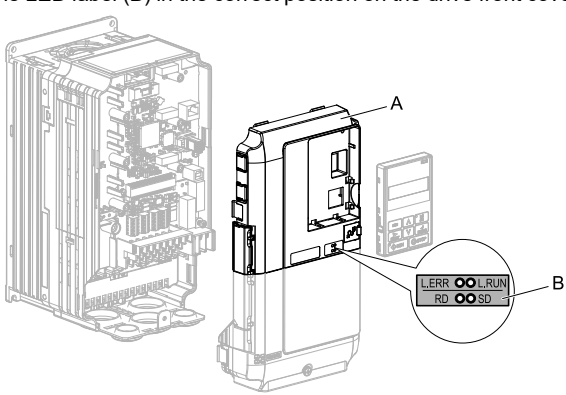
NOTICE *Damage to Equipment. When you touch the option, make sure that you observe correct electrostatic discharge (ESD) procedures. If you do not follow procedures, it can cause ESD damage to the drive circuitry.*



A - Drive front cover
B - Keypad
C - Drive terminal cover

Figure 5.2 Remove the Keypad, Front Cover, and Terminal Cover

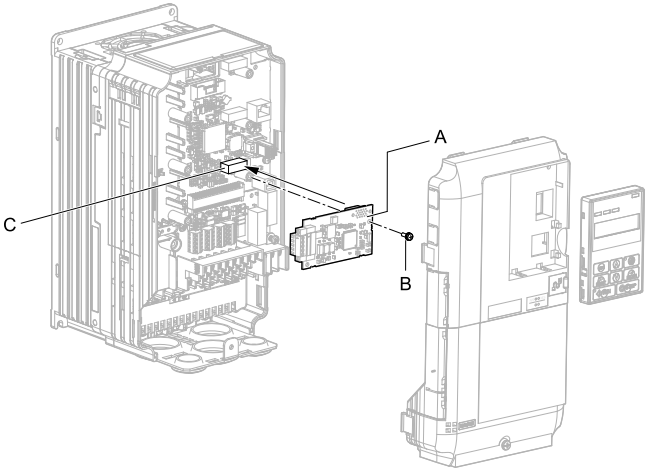
2. Put the LED label (B) in the correct position on the drive front cover (A).



A - Drive front cover
B - LED label

Figure 5.3 Put the LED Label on the Drive Front Cover

3. Install the option (A) into the CN5-A connector (C) on the drive and use the included screws (B) to put it in place.



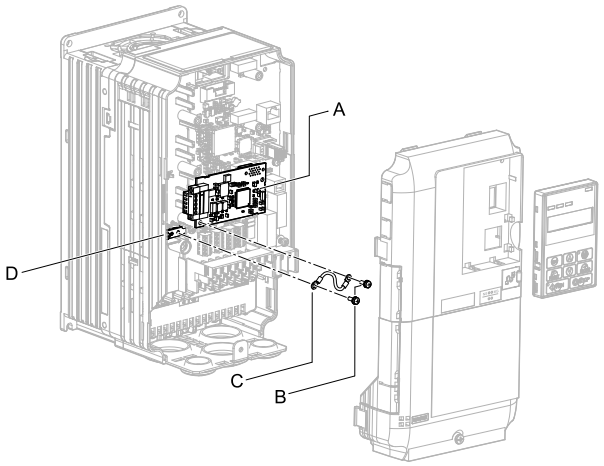
A - Option
B - Included screw
C - Connector CN5-A

Figure 5.4 Install the Option

4. Use one of the remaining included screws (B) to connect one end of the ground wire (C) to the ground terminal (D). Use the last remaining included screw (B) to connect the other end of the ground wire (C) to the remaining ground terminal and installation hole on the option (A).

   Tighten the screws to a correct tightening torque:

   • 0.5 N·m to 0.6 N·m (4.4 lbf·in to 5.3 lbf·in)



A - Option
B - Included screws
C - Ground wire
D - Drive grounding terminal (FE)

Figure 5.5 Connect the Ground Wire

Note:
The drive has only two ground terminal screw holes. When you connect three options, two options will share one ground terminal.

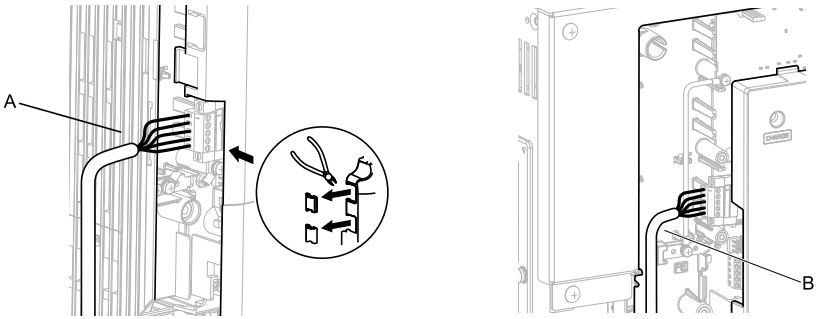
5. Route the option wiring.

   Procedures to wire the option are different for different drivel models.

   - You can route the option wiring through openings on the front cover of some models. Remove the perforated tabs on the left side of the front cover as shown in Figure 5.6-A to create the necessary openings on these models. To prevent damage to the cable from the cut end, treat the cut surface with sandpaper.
   - Route the option wiring inside the enclosure as shown in Figure 5.6-B.

   Refer to the drive manuals for more information.

Note:
- Isolate communication cables from main circuit wiring and other electrical and power lines.
- Connect the terminator (model No.: JEPMC-W6022-E) to the option modular connector (CN1) on the end drive of the communication lines.



A - Route wires through the openings provided on the left side of the front cover. *1

B - Use the open space provided inside the drive to route option wiring.

Figure 5.6 Wire Routing Examples

*1 If there is wiring outside the enclosure, the drive will not meet Enclosed wall-mounted type (IP20/UL Type 1) requirements.

6. Firmly connect the CC-Link communication cable to the option modular connector (CN1).

   Isolate communication cables from main circuit wiring and other electrical and power lines. Make sure that you firmly connect the cable end. (Refer to *Option Connection Diagram on page 30*). Refer to *Communication Cable Specifications on page 31* for more information.

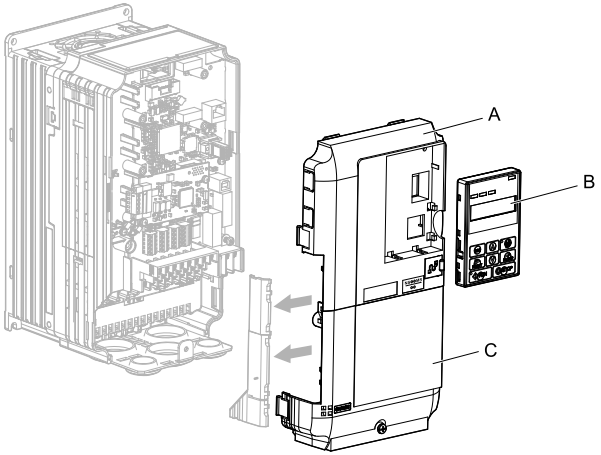
Note:

Do not connect or disconnect the communication cable while the drive is powered up or while the drive is in operation. Failure to obey can cause a static discharge, which will cause the option to stop working correctly. Cycle power on the drive and option to start using the option again.

7. Reattach the front cover (A), terminal cover (C), and keypad (B).

   Refer to the drive manuals for more information.

NOTICE *Do not pinch cables between the front covers and the drive. Failure to comply could cause erroneous operation.*



A - Drive front cover
B - Keypad
C - Drive terminal cover

Figure 5.7 Replace the Front Cover, Terminal Cover, and Keypad

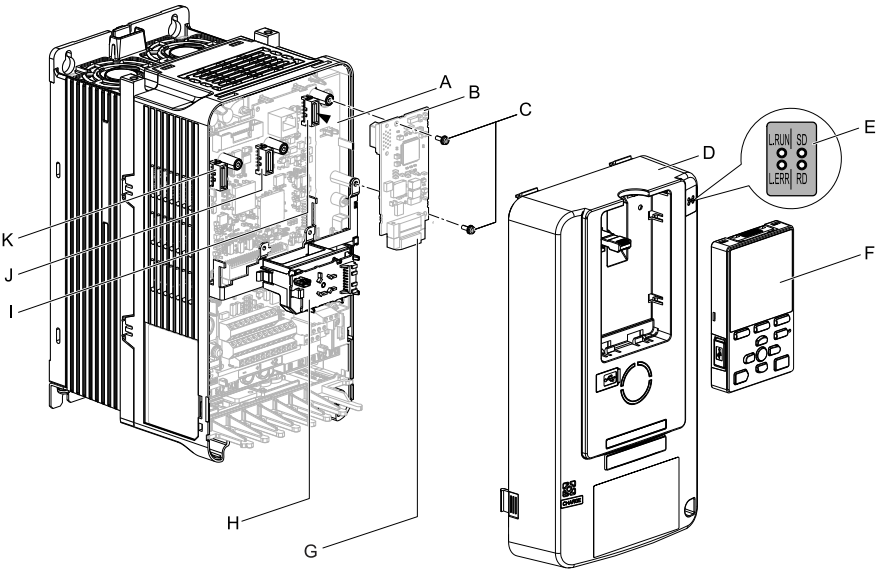
8. Set drive parameters in *Related Drive Parameters on page 34* for correct option performance.

■ Procedure B

This section shows the procedure to install and wire the option on a GA700 or GA800 drive.

Prepare the Drive for the Option

Correctly wire the drive as specified by the manual packaged with the drive. Make sure that the drive functions correctly. Refer to the drive manuals for more information.



A - **Insertion point for CN5 connector**
B - **Option**
C - **Included screws**
D - **Drive front cover**
E - **LED label**
F - **Keypad**
G - **Option modular connector CN1**
H - **LED Status Ring board**
I - **Connector CN5-A**
J - **Connector CN5-B (Not available for communication option installation.)**
K - **Connector CN5-C (Not available for communication option installation.)**

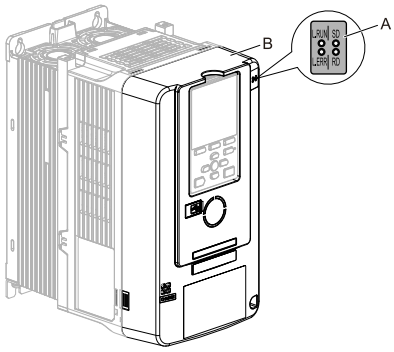
Figure 5.8 Drive Components with Option

Install the Option

Use this procedure to install the option.

⚠ DANGER *Electrical Shock Hazard. Do not examine, connect, or disconnect wiring on an energized drive. Before servicing, disconnect all power to the equipment and wait for the time specified on the warning label at a minimum. The internal capacitor stays charged after the drive is de-energized. The charge indicator LED extinguishes when the DC bus voltage decreases below 50 Vdc. When all indicators are OFF, measure for dangerous voltages to make sure that the drive is safe. If you do work on the drive when it is energized, it will cause serious injury or death from electrical shock.*

1. Put the LED label (A) in the correct position on the drive front cover (B).



A - LED label **B - Drive front cover**

Figure 5.9 Put the LED Label on the Drive Front Cover

2. Remove the keypad (E) and front cover (D).

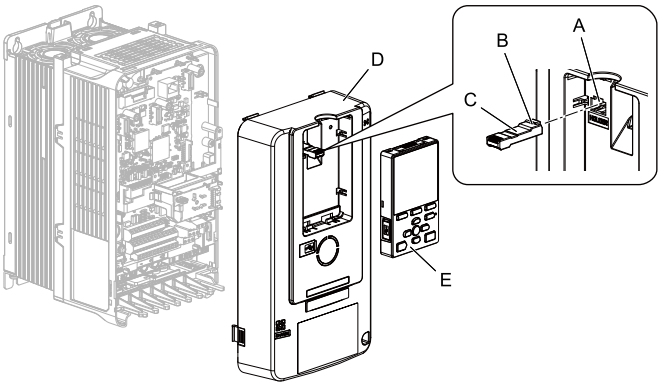
   Shut off power to the drive and wait for the time specified on the drive warning label at a minimum. Make sure that the charge indicator LED is unlit, then remove the keypad and front cover. Refer to the drive manuals for more information.

   You can only install this option into the CN5-A connector on the drive control board.

   NOTICE *Damage to Equipment. When you touch the option, make sure that you observe correct electrostatic discharge (ESD) procedures. If you do not follow procedures, it can cause ESD damage to the drive circuitry.*

Note:

Remove the keypad, then move the keypad connector to the holder on the drive, then remove the front cover.



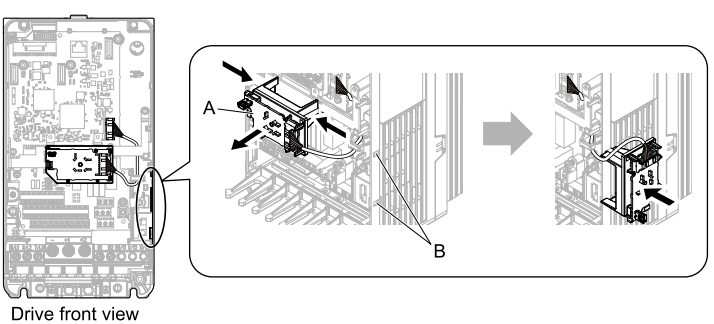
A - Holder
B - Keypad connector tab
C - Keypad connector
D - Drive front cover
E - Keypad

Figure 5.10 Remove the Front Cover and Keypad

3. Carefully remove the LED Status Ring board (A) and put it in the temporary placement holes (B) on the right side of the drive.

   Refer to the drive manuals for more information.

   NOTICE *Do not remove the LED Status Ring board cable connector. If you disconnect the LED Status Ring board, it can cause incorrect operation and damage to the drive.*



Drive front view

A - LED Status Ring board
B - Temporary placement holes

Figure 5.11 Remove the LED Status Ring Board

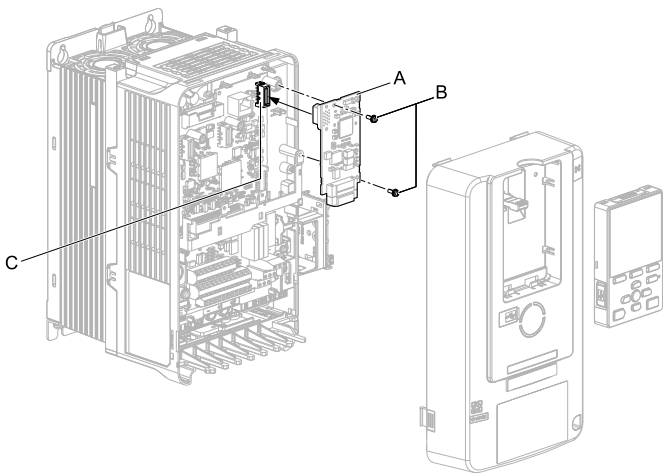
4. Install the option (A) into the CN5-A connector (C) on the drive and use the included screws (B) to put it in place.

   Tighten the screws to a correct tightening torque:

   - 0.5 N·m to 0.6 N·m (4.4 lbf·in to 5.3 lbf·in)

Note:

1. A ground wire is not necessary. Do not use the ground wire.
2. Only two screws are necessary to install the option on GA700 and GA800 drives.
3. The option package contains three screws and one ground wire.



A - Option
B - Included screws
C - Connector CN5-A

Figure 5.12 Install the Option

5. Firmly connect the CC-Link communication cable to the option modular connector (CN1).

   Isolate communication cables from main circuit wiring and other electrical and power lines. Make sure that you firmly connect the cable end. (Refer to *Option Connection Diagram on page 30*). Refer to *Communication Cable Specifications on page 31* for more information.

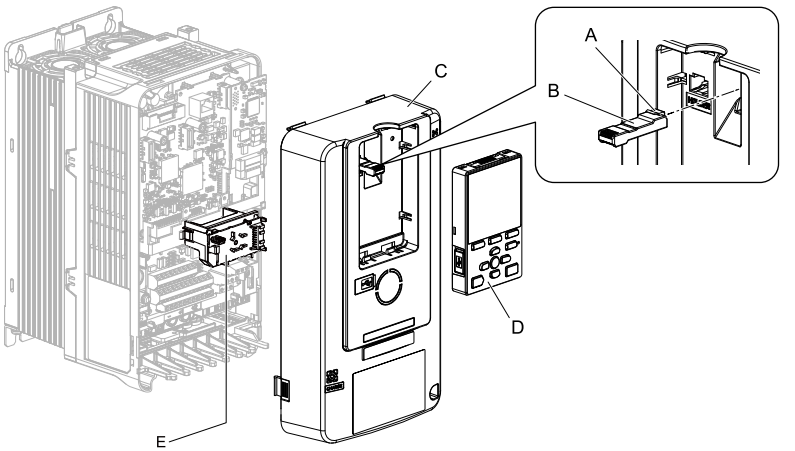
   NOTICE *Damage to Equipment. When you touch the option, make sure that you observe correct electrostatic discharge (ESD) procedures. If you do not follow procedures, it can cause ESD damage to the drive circuitry.*

6. Reattach the LED Status Ring board (E), front cover (C), and keypad (D).

   Refer to the drive manuals for more information.

NOTICE *Do not pinch cables between the front cover or the LED Status Ring board and the drive. Failure to comply could cause erroneous operation.*

Note:
- Replace the keypad connector then install the keypad.
- Put the keypad connector tab into the holder when you install the keypad connector to the holder.



A - Keypad connector tab
B - Keypad connector
C - Drive front cover
D - Keypad
E - LED Status Ring board

Figure 5.13 Install the LED Status Ring board, Front Cover, and Keypad

7. Set drive parameters in *Related Drive Parameters on page 34* for correct option performance.

◆ Communication Cable Specifications

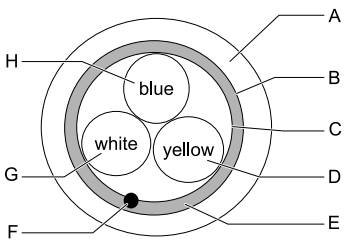
Use only CC-Link dedicated communication cable. The Yaskawa warranty does not cover other cable types. For more information on cables, refer to the CC-Link website at http://www.cc-link.org/.

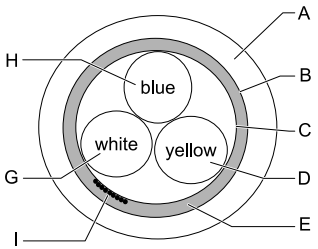
Yaskawa recommends using CC-Link cables suitable for the conditions listed in the following table.

Table 5.2 Communication Cable Requirements

Item	Specifications
Cable Type	triple-core shielded twisted-pair cable
External Diameter	8.0 mm maximum

Item			Specifications
Drain Wire			20 lines/0.18 mm or 24 lines/0.18 mm
Electrical Characteristics	Conductor Resistance (20° C (68°F))		37.8 Ω/km
	Insulation Resistance		10000 MΩ·km or greater
	Voltage Tolerance		500 Vdc, 60 s
	Capacitance (1 kHz)		60 nF/km maximum
	Impedance	1 MHz	110 ±15 Ω
		5 MHz	110 ±6 Ω
	Attenuation (20°C (68°F))	1 MHz	1.6 dB/100 m maximum
		5 MHz	3.5 dB/100 m maximum





A - Sheath
B - Shield
C - Aluminum tape
D - DG (yellow)
E - Ground
F - Drain (solid/non-stranded)
G - DB (white)
H - DA (blue)
I - Drain (stranded wire)

Figure 5.14 CC-Link Cable Diagram

◆ Option Connection Diagram

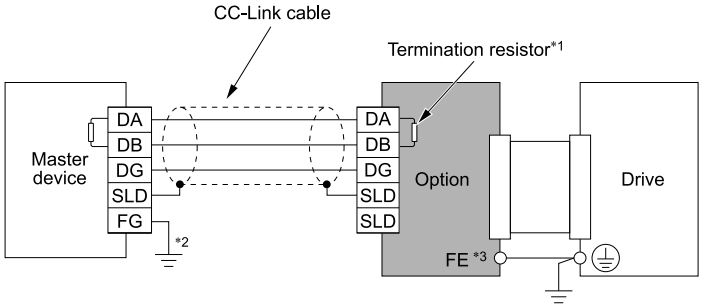


Figure 5.15 Using a Single Drive

*1 The option must be configured with a termination resistor. Refer to *Termination Resistor Connection on page 33* for more information.

*2 Make sure that the FG terminal on the master drive is grounded properly.

*3 Connect the included ground wire for installations on 1000-series drives and GA500 drives.

The ground wire is not necessary for installation on GA700 or GA800 drives.

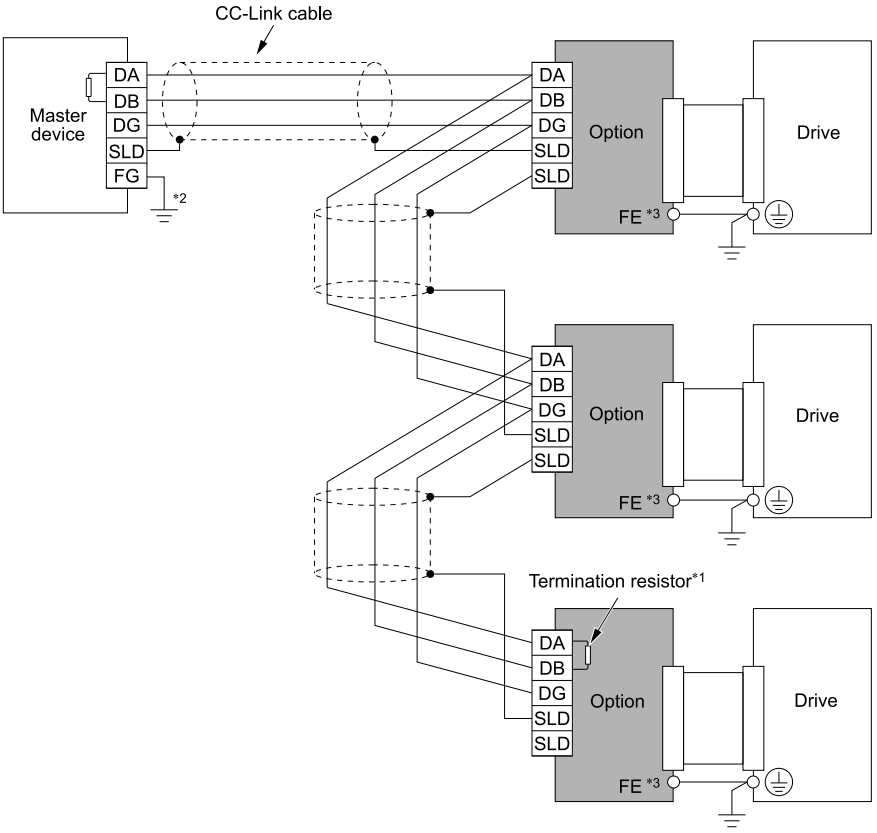


Figure 5.16 Using Multiple Drives

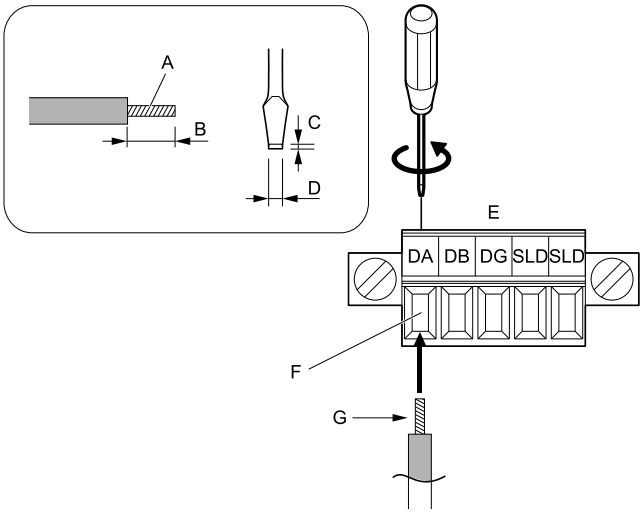
*1 The option must be configured with a termination resistor. Refer to *Termination Resistor Connection on page 33* for more information.
*2 Make sure that the FG terminal on the master drive is grounded properly.
*3 Connect the included ground wire for installations on 1000-series drives and GA500 drives.
The ground wire is not necessary for installation on GA700 or GA800 drives.

◆ Communication Cable Specifications

⚠ WARNING *Fire Hazard. Tighten all terminal screws to the correct tightening torque. Connections that are too loose or too tight can cause incorrect operation and damage to the drive. Incorrect connections can also cause death or serious injury from fire.*

Route the option wiring as specified by these procedures.

1. Connect the communication cables to the option modular connector CN1 as shown in Figure 5.17.



A - Pull back the shielding and lightly twist the end with your fingers to keep the ends from fraying.
B - About 5.5 mm (when not using terminal extensions)
C - Blade thickness of 0.4 mm or less
D - Blade width of 2.5 mm or less
E - Option modular connector CN1
F - CC-Link comm cable (do not soldered ends)
G - Loosen the screws and insert the cable into the opening on the terminal block

Figure 5.17 Connect Cable Wiring

2. Make sure that you correctly connect the wires and that you did not accidentally pinch wire insulation in the option modular connector CN1.

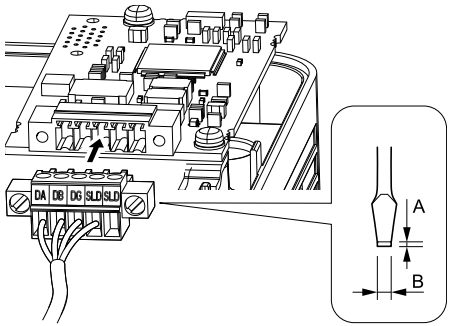
   Trim any frayed wires.

3. Connect the communication cables to the option modular connector CN1 as shown in Figure 5.18.

   After the option modular connector CN1 is fully attached to the option, tighten the screws on the left and right sides of the option modular connector CN1.

   Tighten the screws to a correct tightening torque:

   - 0.22 N·m to 0.25 N·m (1.95 lbf·in to 2.21 lbf·in)



A - Blade depth of 0.6 mm or less **B - Blade width of 3.5 mm or less**

Figure 5.18 Option Modular Connector CN1 Installation (Ex. GA700)

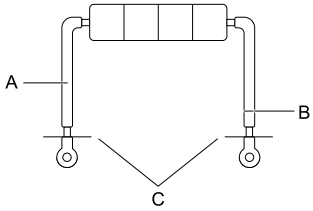
◆ Termination Resistor Connection

When the CC-Link Option is the last station connected in a CC-Link network, the termination resistor needs to be installed on that CC-Link Option.

Cut the ring lugs from the termination resistor leads, and then loosen the DA and DB terminals and insert the termination resistor between terminals DA and DB as shown.

Note:

Use the built-in termination resistor from the master if available, otherwise procure a standard-market resistor of 110 Ω, ±5% (1/2 W).



A - Jumper
B - Cut here
C - Cut (removes approximately 5.5 mm (0.21 in) of the covering at the tip.)

Figure 5.19 Termination Resistor

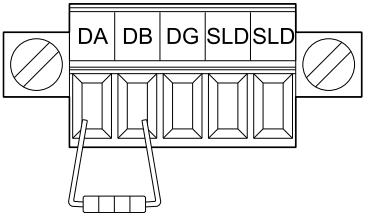


Figure 5.20 Termination Resistor Wiring

6 Related Drive Parameters

These parameters set the drive for operation with the option. Make sure that the parameter settings in this table are correct before you start network communications.

Note:

Hex.: MEMOBUS addresses that you can use to change parameters over network communication are represented in hexadecimal numbers.

No. (Hex.)	Name	Description	Default (Range)
b1-01 (0180)	Frequency Reference Selection 1 (For Drive)	Selects the input method for frequency reference. 0 : Keypad 1 : Analog Input 2 : MEMOBUS/Modbus Communications 3 : Option PCB 4 : Pulse Train Input **Note:** • Set *b1-02 = 3 [Run Command Selection 1 = Option PCB]* to use the master device and serial communications to start and stop the drive. Set *b1-01 = 3* to use the master device to control the frequency reference of the drive. • The default setting is different for different drives. Refer to the instruction manual of your specific drive for more information.	1 (0 - 4)
b1-02 (0181)	Run Command Selection 1 (For Drive, D1000)	Selects the input method for the Run command. 0 : Keypad 1 : Digital Input 2 : MEMOBUS/Modbus Communications 3 : Option PCB **Note:** Set *b1-02 = 3* to start and stop the drive with the master device using serial communications. Set *b1-01 = 3 [Frequency Reference Selection 1 = Option PCB]* to use	1 (0 - 3)

No. (Hex.)	Name	Description	Default (Range)
		the master device to control the frequency reference of the drive.	
b1-18 (0179)	Voltage Reference Source (For D1000)	Selects the voltage reference input source. 0 : Keypad - RUN and STOP keys 1 : Analog Input 2 : Memobus/Modbus Communications 3 : Option 7 : Input Voltage Based Control 1 8 : Input Voltage Based Control 2 **Note:** • On D1000, to use the CC-Link master device as the voltage reference, set *b1-18 = 3*.	8 (0 - 3, 7, 8)
F6-01 (03A2)	Communication Error Selection (For Drive)	Selects drive response when the drive detects a *bUS [Option Communication Error]* error during communications with the option. 0 : Ramp to Stop 1 : Coast to Stop 2 : Fast Stop (Use C1-09) 3 : Alarm Only 4 : Alarm - Run at d1-04 5 : Alarm - Ramp Stop **Note:** • When you set this parameter to *3* or *4*, the drive will continue operation after it detects a fault. Separately prepare safety protection equipment and systems, for example fast stop switches. • Refer to the drive manual to know if settings *4* and *5* are available. Settings 4 and 5 are available in A1000 software versions PRG: 1021 and later. • The setting range for 1000-Series drives is different for different software versions. Refer to the instruction manual of your specific drive for more information.	1 (0 - 5)
F6-01 (03A2)	Communication Error Selection (For D1000)	Selects drive response when the drive detects a *bUS [Option Communication Error]* error during communications with the option. 1 : Coast to Stop 3 : Alarm Only	1 (1, 3)
F6-02 (03A3)	Comm External Fault (EF0) Detect (For Drive, D1000)	Selects the conditions at which *EF0 [Option Card External Fault]* is detected. 0 : Always Detected 1 : Detected during RUN Only	0 (0, 1)

No. (Hex.)	Name	Description	Default (Range)
F6-03 (03A4)	Comm External Fault (EF0) Select (For Drive)	Selects the operation of the drive when *EF0 [Option Card External Fault]* is detected. 0 : Ramp to Stop 1 : Coast to Stop 2 : Fast Stop (Use C1-09) 3 : Alarm Only **Note:** When you set this parameter to *3*, the drive will continue operation after it detects a fault. Separately prepare safety protection equipment and systems, for example fast stop switches.	1 (0 - 3)
F6-03 (03A4)	Comm External Fault (EF0) Select (For D1000)	Selects the operation of the drive when *EF0 [Option Card External Fault]* is detected. 1 : Coast to Stop 3 : Alarm Only	1 (1, 3)
F6-04 (03A5)	bUS Error Detection Time (For Drive, D1000)	Sets the delay time for the drive to detect *bUS [Option Communication Error]*. **Note:** • The default setting is 2.0 s, but this default setting will automatically be changed to 0.0 s when the CC-Link option is connected. • When using GA500, the maximum value of *F6-04* is 12.0 s.	0.0 s (0.0 s - 5.0 s)
F6-06 (03A7)	Torque Reference/Limit by Comm (For Drive)	Selects whether to enable or disable the torque reference and torque limit received from the communication option. 0 : Disabled 1 : Enabled **Note:** • Control method availability of this parameter is different for different product series. –1000-Series Parameter is available in *A1-02 = 3, 6, 7 [Control Method Selection = Closed Loop Vector, PM Advanced Open Loop Vector, PM Closed Loop Vector]*. Enabling this parameter allows *d5-01 [Torque Control Selection]* to determine whether the value is read as the Torque Limit value or the Torque Reference value. *d5-01 = 0 [Speed Control]*: Torque Limit *d5-01 = 1 [Torque Control]*: Torque Reference In *A1-02 = 6*, this value is read as the Torque Limit. –GA500 Parameter is available in *A1-02 = 2, 6, 8 [Control Method Selection = Open Loop Vector, PM Advanced Open Loop Vector, EZ Vector Control]*. This value is read as the Torque Limit. –GA700, GA800 Parameter is available in *A1-02 = 2, 3, 4, 6, 7, 8 [Control Method Selection = Open Loop Vector, Closed*	0 (0, 1)

No. (Hex.)	Name	Description	Default (Range)
		Loop Vector, Advanced Open Loop Vector, PM Advanced Open Loop Vector, PM Closed Loop Vector, EZ Vector Control]. Enabling this parameter allows *d5-01 [Torque Control Selection]* to determine whether the value is read as the Torque Limit value or the Torque Reference value. *d5-01 = 0 [Speed Control]*: Torque Limit *d5-01 = 1 [Torque Control]*: Torque Reference In *A1-02 = 2, 8*, this value is read as the Torque Limit. • If the PLC does not supply a torque reference or torque limit when *F6-06 = 1*, the motor cannot rotate.	
F6-06 (03A7)	Torque Reference/Limit by communication option (For D1000)	Enables and disables the torque reference and torque limit received from the communication option. 0 : Disabled 1 : Enabled	0 (0, 1)
F6-07 (03A8)	Multi-Step Ref @ NetRef/ ComRef (For Drive)	0 : Disable Multi-Step References 1 : Enable Multi-Step References **Note:** Default setting is *1* for GA500.	0 (0, 1)
F6-08 (036A)	Comm Parameter Reset @Initialize (For Drive, D1000)	Selects whether communication-related parameters *F6-xx and F7-xx* are set back to original default values when you use parameter *A1-03 [Initialize Parameters]* to initialize the drive. 0 : No Reset - Parameters Retained 1 : Reset Back to Factory Default **Note:** The drive will not change this setting value when you set *F6-08 = 1* and use *A1-03* to initialize the drive.	0 (0, 1)
F6-10 (03B6)	CC-Link Node Address (For Drive, D1000)	Sets the node address for CC-Link communication. Change the parameter then cycle power on the drive. **Note:** • All station addresses must be unique. Do not set this parameter to *0*. Incorrect parameter settings will cause *AEr [Station Address Setting Error]* errors and the L. ERR LED on the option will illuminate. • You can connect up to 42 nodes when all connections are drives. Follow these rules to connect devices that are not drives: – $\{(1 \times a) + (2 \times b) + (3 \times c) + (4 \times d)\} \leq 64$ a : number of drives that occupy 1 node b : number of drives that occupy 2 nodes c : number of drives that occupy 3 nodes d : number of drives that occupy 4 nodes – $\{(16 \times A) + (54 \times B) + (88 \times C)\} \leq 2304$ A : number of remote I/O nodes (64 max)	0 (0 - 64)

No. (Hex.)	Name	Description	Default (Range)
		B : number of remote device nodes (42 max) C : number of local nodes (26 max)	
F6-11 (03B7)	CC-Link Communication Speed (For Drive, D1000)	Sets the communication speed for CC-Link communication. Change the parameter then cycle power on the drive. 0 : 156 kbps 1 : 625 kbps 2 : 2.5 Mbps 3 : 5 Mbps 4 : 10 Mbps	0 (0 - 4)
F6-14 (03BB)	BUS Error Auto Reset (For Drive, D1000)	Sets the automatic reset function for *bUS [Option Communication Errors]*. 0 : Disabled 1 : Enabled	0 (0, 1)

7 Basic Functions

This product is a communication interface to operate, adjust, and monitor the drive as CC-Link remote station with a PLC program. You can use cycle transmission of bit data and word data, which enables high-speed communication at up to 10 Mbps.

This section explains the basic functions to operate using a PLC by CC-Link communication function.

Note:

First, set the parameters to operate the drive using a PLC . Refer to *Related Drive Parameters on page 34* for more information.

◆ Monitor

You can monitor operation status of the drive from a PLC.

Follow the following directions to monitor.

1. Set the monitor code to remote register RW_{W0}.
2. Switch ON the RYC signal (request to execute the monitor code).
   The data according to Monitor Code is stored in the buffer memory of the PLC.

Note:

For a list of monitor codes, write data drives, and setting ranges, refer to the instruction manual for the drive the CC-Link Option is connected to.

◆ Reading and Setting Parameters

The PLC can write drive parameters, read drive data and operation status, and change settings.

Follow the directions below.

1. Set the command code to remote register RW_{W2}.

   Set the write data to RW_{W3} as needed.

2. Switch ON the RYF signal (request to execute the command code).

   - Drive executes the process and reply data that correspond with the command code.
   - Command codes for drive parameters should be calculated by adding the values shown below to the MEMOBUS/Modbus register number.
     Read command code: MEMOBUS/Modbus register + 1000 (Hex.)
     Write command code: MEMOBUS/Modbus register + 2000 (Hex.)
     Example: Acceleration time command code for *C1-01 [Acceleration Time 1]* is 200 (Hex.). Get the read command code by adding 1000 (Hex.), yielding 1200 (Hex.).

Note:

1. For a list of command codes, write data drives, and setting ranges, refer to the instruction manual for the drive the CC-Link Option is connected to.
2. Refer to the MEMOBUS/Modbus Data Table in Appendix C of the instruction manual for the drive the CC-Link option is connected to for a list of monitor data using the MEMOBUS/Modbus message area.

■ Access Method to Parameter of MEMOBUS Register Number 1000 (Hex.) or Later

When setting and reading parameters of the MEMOBUS register number 1000 (Hex.) or later from the PLC, set the MEMOBUS register number 1000 (Hex.) or later to the register number 0C00 (Hex.) to 0C0F (Hex.) from the CC-Link communications. You can access the value of the parameters 1000 (Hex.) or later specified by the MEMOBUS register number 0C00 (Hex.) to 0C0F (Hex.) with the register number 0C80 (Hex.) to 0C8F (Hex.).

This function is available in the option versions PRG:0103 and later.

Table 7.1 List of MEMOBUS Register Numbers and Descriptions

Register No. (Hex.)	Description
0C00	Register number setting 1
0C01	Register number setting 2
0C02	Register number setting 3
0C03	Register number setting 4

Register No. (Hex.)	Description
0C04	Register number setting 5
0C05	Register number setting 6
0C06	Register number setting 7
0C07	Register number setting 8
0C08	Register number setting 9
0C09	Register number setting 10
0C0A	Register number setting 11
0C0B	Register number setting 12
0C0C	Register number setting 13
0C0D	Register number setting 14
0C0E	Register number setting 15
0C0F	Register number setting 16
0C80	Parameter contents of register number in setting 1
0C81	Parameter contents of register number in setting 2
0C82	Parameter contents of register number in setting 3
0C83	Parameter contents of register number in setting 4
0C84	Parameter contents of register number in setting 5
0C85	Parameter contents of register number in setting 6
0C86	Parameter contents of register number in setting 7
0C87	Parameter contents of register number in setting 8
0C88	Parameter contents of register number in setting 9
0C89	Parameter contents of register number in setting 10
0C8A	Parameter contents of register number in setting 11
0C8B	Parameter contents of register number in setting 12
0C8C	Parameter contents of register number in setting 13
0C8D	Parameter contents of register number in setting 14

Register No. (Hex.)	Description
0C8E	Parameter contents of register number in setting 15
0C8F	Parameter contents of register number in setting 16

The example below shows reading and setting parameters.

- Example 1: When setting 256 (100 (Hex.)) to the parameter of the MEMOBUS register number 1200 (Hex.)
  - Write the register number (1200 (Hex.)) that you want to set to register number 0C00 (Hex.) (register number setting 1).
  - Write the value (100 (Hex.)) to be written to register number 1200 (Hex.) in register number 0C80 (Hex.).

  These are the details for settings and readings:

  1. Set the command code (2C00 (Hex.)) to remote register RW_{W2}.
  2. Set the write data (1200 (Hex.)) to remote register RW_{W3}.
  3. Switch ON the RYF signal (request to execute the command code).
  4. Set the command code (2C80 (Hex.)) to remote register RW_{W2}.
  5. Set the write data (100 (Hex.)) to remote register RW_{W3}.
  6. Switch ON the RYF signal (request to execute the command code).
     256 (100 (Hex.)) is set to the parameter of register number 1200 (Hex.).
- Example 2: When reading the parameter of the MEMOBUS register number 1500 (Hex.) with the register number setting 9
  - Write the register number (1500 (Hex.)) that you want to set to register number 0C08 (Hex.) (register number setting 9).
  - Read the value of the register number 1500 (Hex.) from the register number 0C88 (Hex.).

  Details for settings and readings are as follows:

  1. Set the command code (2C08 (Hex.)) to remote register RW_{W2}.
  2. Set the write data (1500 (Hex.)) to remote register RW_{W3}.
  3. Switch ON the RYF signal (request to execute the command code).
  4. Set the command code (1C88 (Hex.)) to remote register RW_{W2}.
  5. Switch ON the RYF signal (request to execute the command code).
     The parameter value of register number 1500 (Hex.) is stored in remote register RW_{R3}.

8 CC-Link Data List

◆ Remote I/O

The drive takes up a single station address in the buffer memory or the PLC. The table below shows the drive I/O as seen from the PLC side.

Note:

1. Remote I/O data varies between drives and D1000.
2. Refer to the PLC's programming manual for information on the PLC's buffer memory.

■ Drive Remote I/O

PLC → Drive

Table 8.1 Remote I/O List (PLC → Drive)

Signal	Name	Description	Comments (Default)
RY0	Forward Run	ON: Forward Run Command OFF: Stop Command	-
RY1	Reverse Run	ON: Reverse Run Command OFF: Stop Command	-
RY2	Terminal S3 Function	Multi-Function Input: H1-03 [Terminal S3 Function Selection]	H1-03 = 24 [External Fault]
RY3	Terminal S4 Function	Multi-Function Input: H1-04 [Terminal S4 Function Selection]	H1-04 = 14 [Fault Reset]
RY4	Terminal S5 Function	Multi-Function Input: H1-05 [Terminal S5 Function Selection]	H1-05 = 3 [Multi-Step Speed 1]
RY5	Terminal S6 Function	Multi-Function Input: H1-06 [Terminal S6 Function Selection]	H1-06 = 4 [Multi-Step Speed 2]
RY6	Terminal S7 Function	Multi-Function Input: H1-07 [Terminal S7 Function Selection]	H1-07 = 6 [Jog Reference]
RY7	1000-Series, GA700, GA800: Terminal S8 Function GA500: Reserved	1000-Series, GA700, GA800: Multi-Function Input: H1-08 [Terminal S8 Function Selection] GA500: -	1000-Series, GA700, GA800: H1-08 = 8 [Baseblock command (N.O.)] GA500: -
RY8	Reserved	-	-
RY9	Drive Output Interrupt	ON: Motor coasts to stop. OFF: Drive will begin operating as soon as a Run command is given.	-
RYA	External Fault	ON: EF0 [Option Card External Fault]	-

Signal	Name	Description	Comments (Default)
RYB	Motor Revolutions / Output Frequency Switch	Sets data contents for the remote register RW_{R1}. ON: Output Frequency OFF: Motor revolutions	Disabled in V/f Control or PM Open Loop Vector mode. RW_{R1} is the output frequency.
RYC	Monitor Reference	ON: Monitor data specified in the monitor code is set to remote register RW_{R0}.	When switching between monitors using RYC (Monitor Reference), RYC needs to be turned OFF and then back ON again after the monitor code has been changed.
RYD	Frequency Reference 1	Frequency set to remote register RW_{W1} becomes the operating frequency for the drive.	When switching ON RYD, the frequency in the remote register RW_{W1} will always reflect the operating frequency for the drive.
RYE	Frequency Reference 2	Sets the frequency in the remote register RW_{W1} to parameter *d1-01 [Frequency Reference 1]* and as the drive's main frequency reference at the same time. **Note:** If the frequency reference is set to be provided by the keypad (i.e. *b1-01 = 0 [Frequency Reference Selection 1 = Keypad]*), then switching ON RYE changes the frequency reference.	All parameter settings are saved when this flag is switched ON. Triggered by the rising edge of the signal.
RYF	Command Code Execute Request	Request to execute the command code.	Triggered by the rising edge of the signal.
RY10 - 13	Reserved	-	-
RY14	Terminal S1 Function	Multi-Function Input: H1-01 [Terminal S1 Function Selection]	Function is disabled when for *H1-01 = 40 [Forward Run Command = Forward RUN (2-Wire)]*.
RY15	Terminal S2 Function	Multi-Function Input: H1-02 [Terminal S2 Function Selection]	Function is disabled when for *H1-01 = 41 [Forward Run Command = Reverse RUN (2-Wire)]*.
RY16 - 19	Reserved	-	-

Signal	Name	Description	Comments (Default)
RY1A	Fault Reset	Resets a drive fault	-
RY1B - 1F	Reserved	-	-

Note:

1. If making frequent setting changes, use RYD (Frequency Reference 1 flag) for setting the register. You can write the EEPROM to the drive a maximum of 100,000 times. Do not use this write command frequently.
2. Although RYE and RYF are triggered by the rising edge of the signal, they are otherwise enabled depending on the value that is input.

Drive → PLC

Table 8.2 Remote I/O List (Drive → PLC)

Signal	Name	Description	Comments (Default)
RX0	Forward Run	ON: Forward Run Command Present (includes DC Injection Braking) OFF: No Forward Run Command	-
RX1	During Reverse	ON: During Reverse OFF: No Reverse Run Command (includes DC Injection Braking)	-
RX2	1000-Series: Terminal M1-M2 Function GA700, GA800: Multi-Function Digital Output 1 Function GA500: Terminal MA/MB-MC Function	Multi-function output: H2-01	1000-Series, GA700, GA800: H2-01 = 0 [Term M1-M2 Function Selection = During Run] GA500: H2-01 = E [Term MA/MB-MC Function Selection = Fault]
RX3	Speed Agree	ON: Output frequency is between frequency reference and the detection width set to *L4-02 [Speed Agree Detection Width]*.	-
RX4	During Stall Prevention	-	-
RX5	During Uv [Undervoltage]	-	-
RX6	1000-Series, GA500: Terminal P1 Function **1* GA700, GA800: Multi-Function	Multi-Function Output: H2-02	1000-Series, GA700, GA800: H2-02 = 1 [Term M3-M4 Function Selection = Zero Speed]

Signal	Name	Description	Comments (Default)
	Digital Output 2 Function *1		GA500: H2-02 =0 [Terminal P1-C1 Function Selection During Run]
RX7	1000-Series, GA500: Terminal P2 Function *1 GA700, GA800: Multi-Function Digital Output 3 Function *1	Multi-Function Output: H2-03	1000-Series, GA700, GA800: H2-03 = 2 [Term M5-M6 Function Selection = Speed Agree 1] GA500: H2-03 = 2 [Terminal P2-C2 Function Selection = Speed Agree 1]
RX8, 9	Reserved	-	-
RXA	CC-Link Option Fault	Communication error between drive and CC-Link device	-
RXB	Monitoring Motor Revolutions	ON: Currently monitoring motor revolutions.	Data is stored in remote register RW_{R1}.
RXC	Obtain Monitor Data	ON: Monitor data has been updated.	-
RXD	Frequency Setting Ready 1	ON: Displays the main frequency reference that has been set.	-
RXE	Frequency Setting Ready 2	ON: Displays the data set to *d1-01 [Frequency Reference 1]*. **Note:** Also sets the main frequency reference at the same time.	-
RXF	Command Code Execute Complete	ON: Displayed after the specified command code has been executed. RXF signal switches OFF when the RYF command is no longer present.	-
RX10 - 19	Reserved	-	-
RX1A	Error	ON: Fault occurred on the drive side.	-
RX1B	Remote Station Ready	ON: Drive is ready to operate.	-
RX1C - 1F	Reserved	-	-

*1 Terminals are different for different drive models. Refer to *Terminals that Change depending on the Model of the Drive on page 53* for more information.

Note:

If making frequent setting changes, use RYD (Frequency Reference 1 flag) for setting the register. Using RYE (Frequency Reference 2 flag) too often can shorten the performance life of the drive's internal memory.

■ D1000 Remote I/O

PLC → D1000

Table 8.3 Remote I/O List (PLC → D1000)

Signal	Name	Description	Comments (Default)
RY0	Run Command/ Automatic Run Command	ON: Run Command/Automatic Run Command OFF: Stop Command	-
RY1	Forced Run Command	ON: Forced Run Command OFF: Stop Command	-
RY2	Terminal S3 Function	Multi-Function Input: H1-03	H1-03 = 24 [External Fault]
RY3	Terminal S4 Function	Multi-Function Input: H1-04 [Terminal S4 Function Selection]	H1-04 = 14 [Fault Reset]
RY4	Terminal S5 Function	Multi-Function Input: H1-05	H1-05= F [Through Mode]
RY5	Terminal S6 Function	Multi-Function Input: H1-06	H1-06= F [Through Mode]
RY6	Terminal S7 Function	Multi-Function Input: H1-07	H1-07= F [Through Mode]
RY7	Terminal S8 Function	Multi-Function Input: H1-08	H1-08 = 8 [Baseblock command (N.O.)]
RY8	Reserved	-	-
RY9	External Baseblock Command	ON: No converter output	-
RYA	External Fault [EF0]	ON: Option Card External Fault	-
RYB	Reserved	-	-
RYC	Monitor Reference	ON: Monitor data specified in the monitor code is set to remote register RW_{R0}.	When switching between monitors using RYC (Monitor Reference), RYC needs to be turned OFF and then back ON again after the monitor code has been changed.

Signal	Name	Description	Comments (Default)
RYD, E	Reserved	-	-
RYF	Command Code Execute Request	Request to execute the command code.	Triggered by the rising edge of the signal.
RY10	Terminal M1-M2 Function	Multi-Function Relay Output 1 (Terminal M1-M2)	-
RY11	Terminal P1-PC Function *1	Multi-Function Photocoupler Output 1 (Terminal P1-PC)	-
RY12	Terminal P2-PC Function *1	Multi-Function Photocoupler Output 2 (Terminal P2-PC)	-
RY13	Reserved	-	-
RY14	Terminal S1 Function	Multi-Function Input: H1-01	H1-01 = 4B [Run Command]
RY15	Terminal S2 Function	Multi-Function Input: H1-02 [Terminal S2 Function Selection]	H1-02 = 4C [Stop Command]
RY16	RY17 Enabled/ Disabled Selection	-	-
RY17	Term MA/MB-MC Function	Fault Contact Output	-
RY18, 19	Reserved	-	-
RY1A	Fault Reset	Resets a D1000 fault.	-
RY1B - 1F	Reserved	-	-

*1 Terminals are different for different drive models. Refer to *Terminals that Change depending on the Model of the Drive on page 53* for more information.

Note:

Although RYF is triggered by the rising edge of the signal, they are otherwise enabled depending on the value that is input.

D1000 → PLC

Table 8.4 Remote I/O List (D1000 → PLC)

Signal	Name	Description	Comments (Default)
RX0	During Run/During Stop	ON: During Run OFF: Stop	-
RX1	During Regeneration	ON: During Regeneration	-

Signal	Name	Description	Comments (Default)
RX2	Terminal M1-M2 Function	Multi-function output: H2-01 [Terminal M1-M2 Function Selection]	H2-01 = 25
RX3	During Run (Converter Ready)	-	-
RX4	Reserved	-	-
RX5	Uv [Undervoltage]	-	-
RX6	Terminal P1-PC Function *1	Multi-function output: H2-02 [Terminal P1-PC Function Selection]	H2-02 = 26 [During MC ON]
RX7	Terminal P2-PC Function *1	Multi-function output: H2-03 [Terminal P2-PC Function Selection]	H2-03 = 6 [Converter Ready]
RX8	Momentary Power Loss Ride-Thru/ Power Loss Recovery	-	-
RX9	ComCtrlstatus/ NetCtrlstatus	-	-
RXA	CC-Link Option Fault	Communication error between D1000 and CC-Link device	-
RXB	During Active Current Limit	-	-
RXC	Obtain Monitor Data	ON: Monitor data has been updated.	-
RXD	Alarm	-	-
RXE	Fault	-	-
RXF	Command Code Execute Complete	ON: Displayed after the specified command code has been executed. RXF signal switches OFF when the RYF command is no longer present.	-
RX10	During Reset Signal Input	-	-
RX11	oPE Error	-	-
RX12	AUv [Power Supply Undervoltage]	-	-
RX13 - 19	Reserved	-	-
RX1A	Error	ON: Fault occurred on the D1000 side.	-

Signal	Name	Description	Comments (Default)
RX1B	Remote Station Ready	ON: D1000 is ready to operate.	-
RX1C - 1F	Reserved	-	-

*1 Terminals are different for different drive models. Refer to *Terminals that Change depending on the Model of the Drive on page 53* for more information.

◆ Remote Register

Note:

Remote register data varies between drives and D1000 that support this option.

■ Drive Remote Register

PLC → Drive

Table 8.5 Remote Register (PLC → Drive)

Remote Register	Name	Description	Request Flag
RW_{W0}	Monitor Code	• Sets the code number of the items to be displayed by the monitor. • The monitor value is stored in register RW_{R0} by enabling RYC (the monitor execution request flag) after the monitor code has been set. • While RW_{R0} is updated, RXC (during monitor flag) remains ON.	RYC (Monitor Execute Request)
RW_{W1}	Frequency Setting	• Specifies the source of the frequency reference. The value set to this register becomes the main frequency reference when RYD (frequency setting reference 1) is enabled. • When RYE (frequency setting reference 2 flag) is enabled, then the value for frequency reference 1 is written and saved to EEPROM *1. **Note:** Parameter *o1-03 [Frequency Display Unit Selection]* determines the setting drives for the frequency reference.	• RYD (Frequency Reference 1) • RYE (Frequency Reference 2)

Remote Register	Name	Description	Request Flag
RW_{W2}	Command Code	• Sets the command code to execute functions, for example the fault reset, fault history, and parameter read. **Note:** Refer to the MEMOBUS/Modbus Data Table in Appendix C of the instruction manual for the drive the CC-Link option is connected to for a list of monitor data using the MEMOBUS/Modbus message area. • When RYF (command code execution request flag) is enabled, the drive executes the specified command. When the command is carried out, RXF switches ON. **Note:** Adjust the value set to RW_{W3} (write data)to match changes to any parameter settings.	RYF (Command Code Execute Request)
RW_{W3}	Write Data	• Sets the value to be used along with RW_{W2} (Command Code) as needed. • You must enable RYF (command code execution request flag)after the command code and write data have been set.	

*1 You can write data to the EEPROM used for the drive 100,000 times. Do not use this write command frequently.

Drive → PLC

Table 8.6 Remote Register (Drive → PLC)

Remote Register	Name	Description	Check Flag
RW_{R0}	Monitor Data	• Monitor data is stored according to RW_{W0} (Monitor Code). • Monitor data is updated while RYC (monitor execute request flag) is enabled. RXC (while monitoring) remains ON as data is updated.	RXC (while monitoring)
RW_{R1}	Output Frequency	• Motor revolutions or output frequency has been set without errors. Sets data contents with RYB (Motor Revolutions/ Output Frequency Switch). • When RYB is disabled, the output frequency are stored. Set in the drives specified by *o1-03 [Frequency Display Unit Selection]* in output frequency. Example: When *o1-03 = 0 [0.01 Hz]*, the frequency is displayed in 0.01 Hz. When *o1-03 = 2 [min^{-1}(r/min) units]*, the frequency is displayed as min^{-1}.	RXB (actual motor rotations)

Remote Register	Name	Description	Check Flag
		• When RYB is enabled, the motor revolutions are stored as min^{-1}. Here, RXB (actual motor rotations) is enabled. • The output frequency are stored in V/f Control or PM Open Loop Vector mode. RYB setting is disabled.	
RW_{R2}	Response Code:	• Sets 00 (Hex.) when there are no problems with RW_{W2} (Command Code) and RW_{W3} (Write Data). • Sets 01 (Hex.) through 03 (Hex.) if an error occurs. • Response Code: 00 (Hex.): Normal 01 (Hex.): Write-mode error (attempted to write during run, etc.) 02 (Hex.): Command code error 03 (Hex.): Data setting range error	RXF (Command Code Execute Complete)
RW_{R3}	Read Data	Data is set according to the command code.	

Data in RW_{R1} (Output Frequency) and Units

Table 8.7 Drive RW_{R1} (Output Frequency) Data List

Conditions		Drive → PLC		
A1-02 [Control Method Selection]	RYB (Motor Revolutions/ Output Frequency Switch)	RXB (Actual Motor Rotations)	RW_{R1} Data	RW_{R1} Units
0, 5 *1	-	OFF (output frequency)	Output Frequency	Set in the drives specified by *o1-03 [Frequency Display Unit Selection]* in output frequency.
1, 2, 3, 4, 6, 7, 8	OFF (motor revolutions)	ON (motor revolutions)	Motor revolutions	min^{-1}
	ON (output frequency)	OFF (output frequency)	Output Frequency	Set in the drives specified by *o1-03 [Frequency Display Unit Selection]* in output frequency.

*1 Controls in the same way as *A1-02 = 1 [Control Method Selection = V/f Control with Encoder]* in *A1-02 = 0 [V/f Control]* and *H6-01 = 3 [Terminal RP Pulse Train Function = Speed Feedback (V/F Control)]*.

Table 8.8 RW_{R1} (Output Frequency) Units List

o1-03 [Frequency Display Unit Selection]	Frequency Reference Units (RW_{R1})
0	0.01 Hz units (output frequency)
1	0.01% units (percent of maximum output frequency)
2	min^{-1} units (calculated from the maximum output frequency and the number of motor poles)
3	User-set (according to parameter *o1-10 [User Units Maximum Value]*, and *o1-11 [User Units Decimal Position]*)

Note:

Refer to the instruction manual for the drive the CC-Link Option is connected to for more details on parameter settings.

■ D1000 Remote Register

PLC → D1000

Table 8.9 Remote Register (PLC → D1000)

Remote Register	Name	Description	Request Flag
RW_{W0}	Monitor Code	• Sets the code number of the items to be displayed by the monitor. • The monitor value is stored in register RW_{R0} by enabling RYC (the monitor execution request flag) after the monitor code has been set. • While RW_{R0} is updated, RXC (during monitor flag) remains ON.	RYC (Monitor Execute Request)
RW_{W1}	Reserved	-	-
RW_{W2}	Command Code	• Sets the command code to execute functions, for example the fault reset, fault history, and parameter read. **Note:** Refer to the MEMOBUS/Modbus Data Table in Appendix C of the instruction manual for D1000 the CC-Link option is connected to for a list of monitor data using the MEMOBUS/Modbus message area. • When RYF (command code execution request flag) is enabled, the drive executes the specified command. When the command is carried out, RXF switches ON. **Note:** The value set to RW_{W3} (write data) should be adjusted accordingly to match changes to any parameter settings.	RYF (Command Code Execute Request)

Remote Register	Name	Description	Request Flag
RW_{W3}	Write Data	• Sets the value to be used along with RW_{W2} (Command Code) as needed. • Enable RYF (command code execution request flag) after you set the command code and write data.	

Note:

Use the extended command code 280 (Hex.) to set the DC bus voltage reference.

D1000 → PLC

Table 8.10 Remote Register (D1000 → PLC)

Remote Register	Name	Description	Check Flag
RW_{R0}	Monitor Data	• Monitor data is stored according to RW_{W0} (Monitor Code). • Monitor data is updated while RYC (monitor execute request flag) is enabled. RXC (while monitoring) remains ON as data is updated.	RXC (while monitoring)
RW_{R1}	Reserved	-	-
RW_{R2}	Response Code:	• Sets 00 (Hex.) when there are no problems with RW_{W2} (Command Code) and RW_{W3} (Write Data). • Sets 01 (Hex.) through 03 (Hex.) if an error occurs. • Response Code: 00 (Hex.): Normal 01 (Hex.): Write-mode error (attempted to write during run, etc.) 02 (Hex.): Command code error 03 (Hex.): Data setting range error	RXF (Command Code Execute Complete)
RW_{R3}	Read Data	Data is set according to the command code.	

Note:

Use the monitor code 0008 (Hex.) to set the DC bus voltage feedback.

◆ Terminals that Change depending on the Model of the Drive

The table below lists terminals that change depending on the model of the drive.

Table 8.11 Terminals that Change depending on the Model of the Drive

Drive	Name	Terminal	Drive Model
1000-Series	Multi-Function Contact Output	M1-M2	All

Drive	Name	Terminal	Drive Model
	Multi-Function Photocoupler Output 1	P1-PC	CIMR-xAx, CIMR-xTx, CIMR-xKx, CIMR-xBx *1, CIMR-xDx
		M3-M4	CIMR-xUx, CIMR-xCx
	Multi-Function Photocoupler Output 2	P2-PC	CIMR-xAx, CIMR-xTx, CIMR-xKx, CIMR-xBx *2, CIMR-xDx
		M5-M6	CIMR-xUx, CIMR-xCx
GA500	Multi-Function Contact Output	MA-MB-MC	All
	Multi-Function Photocoupler Output 1	P1-PC	All
	Multi-Function Photocoupler Output 2	P2-PC	All
GA700	Multi-Function Digital Output 1	M1-M2	All
	Multi-Function Digital Output 2	M3-M4	All
	Multi-Function Digital Output 3	P1-C1	CIPR-GA70Ax, CIPR-GA70Tx
		M5-M6	CIPR-GA70Ux, CIPR-GA70Cx, CIPR-GA70Bx, CIPR-GA70Kx, CIPR-GA70Dx
	Multi-Function Digital Output 4	P2-C2	CIPR-GA70Ax, CIPR-GA70Tx
GA800	Multi-Function Digital Output 1	M1-M2	All
	Multi-Function Digital Output 2	M3-M4	All
	Multi-Function Digital Output 3	M5-M6	All

*1 Terminals will change to M3-M4 depending on the model type of CIMR-xBx. Refer to the drive manuals for more information.

*2 Terminals will change to M5-M6 depending on the model type of CIMR-xBx. Refer to the drive manuals for more information.

9 Troubleshooting

◆ Drive-Side Error Codes

Drive-side error codes appear on the drive keypad. *Faults on page 55* lists causes of the errors and possible corrective actions. Refer to the drive Technical Manual for additional error codes that can appear on the drive keypad.

■ Faults

Both *bUS [Option Communication Error]* and *EF0 [Option Card External Fault]* can appear as a fault. When a fault occurs, the keypad ALM LED stays lit. The ALM LED also illuminates. When an alarm occurs, the ALM LED flashes.

If communication stops while the drive is running, answer these questions to help fix the problem:

- Is the communication line properly connected to the option? Is it loose?
- Is the CC-Link communication cable properly connected to the option?
- Is the PLC program working? Is the controller/PLC CPU stopped?
- Did a momentary power loss interrupt communications?

Code	Name	Causes	Possible Solutions
bUS	Option Communication Error	The drive did not receive a signal from the controller.	• Check for wiring errors. • Correct the wiring.
		The communications cable wiring is incorrect.	
		An existing short circuit or communications disconnection	Check disconnected cables and short circuits and repair as needed
		A data error occurred due to electric interference	• Prevent noise in the control circuit, main circuit, and ground wiring. • If you identify a magnetic contactor as a source of noise, install a surge absorber to the contactor coil. • Use only recommended cables or other shielded line. Ground the shield on the controller side or the drive input power side. • Separate all communication wiring from drive power lines. Install an EMC noise filter to the drive power supply input. • Decrease the effects of electrical interference from the controller.
		Option is damaged	If there are no problems with the wiring and the error continues to occur, replace the option.
		Connection Time-out	Check if the CPU of the controller is not stopped.
		Duplicate IP Address found on network	Change to a different IP address. If *F7-13 = 0 [Address Mode at Startup = Static]*, change parameters *F7-01 to F7-04 [IP Address 1 to 4]*.

Code	Name	Causes	Possible Solutions
EF0	Option Card External Fault	The option received an external fault from the controller.	1. Find the device that caused the external fault and remove the caus. 2. Clear the external fault input from the controller.
		A programming error occurred on the controller side.	Examine the operation of the controller program.
oFA00	Option Not Compatible with Port	The option connected to connector CN5-A is not compatible.	Connect the option to the correct connector. • Use connector CN5-A when you connect the option. To use other options, refer to those option manuals.
oFA01	Option Card Fault (CN5-A)	The option connected to option port CN5-A was changed during run.	1. De-energize the drive. 2. Connect the option to the correct option port.
oFA03, oFA04	Option Card Error (CN5-A)	A fault occurred in the option.	1. De-energize the drive. 2. Make sure that the option is correctly connected to the connector. 3. If the problem continues, replace the option.
oFA30 to oFA43	Option Card Connection Error (CN5-A)	A fault occurred in the option.	1. De-energize the drive. 2. Make sure that the option is correctly connected to the connector. 3. If the problem continues, replace the option.
oFb00	Option Not Compatible with Port	The option connected to connector CN5-B is not compatible.	Connect the option to the correct connector. • Use connector CN5-A when you connect the option. To use other options, refer to those option manuals.
oFb02	Option Fault	An option of the same type is already installed in option port CN5-A, CN5-B, or CN5-C.	Connect the option to the correct option port.
oFC00	Option Fault (CN5-B)	The option connected to connector CN5-C is not compatible.	Connect the option to the correct connector. • Use connector CN5-A when you connect the option. To use other options, refer to those option manuals.
oFC02	Option Fault	An option of the same type is already installed in option port CN5-A, CN5-B, or CN5-C.	Connect the option to the correct option port.

■ Minor Faults and Alarms

Code	Name	Causes	Possible Solutions
AEr	Station Address Error	CANopen Option is set to an address outside the allowable setting range.	Set *F6-35* to an address within the specified range.
CALL	Serial Comm Transmission Error	The communications cable wiring is incorrect.	Correct wiring errors.
		There is a short circuit in the communications cable or the communications cable is not connected.	• Repair the short-circuited or disconnected portion of the cable. • Replace the defective communications cable.
		A programming error occurred on the controller side.	Examine communications at start-up and correct programming errors.
		There is damage to the communications circuitry.	• Do a self-diagnostics check. • If the problem continues, replace the control board or the drive. Contact Yaskawa or your nearest sales representative to replace the control board.
		The termination resistor setting for MEMOBUS/Modbus communications is incorrect.	On the last drive in a MEMOBUS/Modbus network, set DIP switch S2 to the ON position to enable the termination resistor.
CyPo	Cycle Power to Active Parameters	Comm. Option Parameter Not Upgraded	Re-energize the drive to update the communication option parameters. **Note:** If the option software version is not compatible or if you install an incorrect option to the drive, it will trigger an alarm.

◆ Option LED States

■ How to Check for Errors on LED Lamps

A B

A - 1000-Series **B - GA500, GA700, and GA800**

Figure 9.1 Option LED Labels

Table 9.1 Option LED Display

L.RUN	Lights ON when receiving data normally Lights OFF when timed out wanting to receive
SD	Lights ON when sending data
RD	Lights ON when receiving data
L.ERR	Lights ON when a station address is CRC Error or Abort Error.

Note:

If communication stops while the drive is running, answer these questions to help fix the problem:
- Is the drive properly connected to the option?
- Is the CC-Link communication cable properly connected to the option? Is it loose?
- Is the PLC program properly working? Is the PLC CPU stopped?
- Did a momentary power loss interrupt communications?

■ Faults that Occur with a Single Drive

The example below demonstrates how to read the LED display on the front cover of the drive to determine the cause of a fault and corrective action.

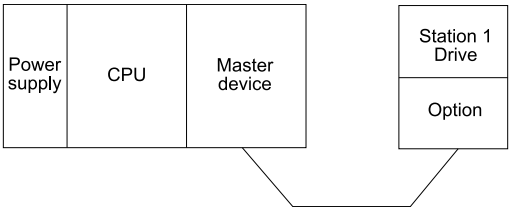


Figure 9.2 Connecting a Single Drive

Table 9.2 LED Fault Display for CC-Link Option with a Single Drive

L.RUN	SD	RD	L.ERR	Cause	Possible Solutions
○	○	○	×	Normal communications	-
○	○	○	□	Error has occurred but communication is normal.	Remove the source of electrical noise interference.
○	○	×	□	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
○	○	×	×	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
○	×	○	□	CRC error with the data received, and no response can be sent	Remove the source of electrical noise interference.

L.RUN	SD	RD	L.ERR	Cause	Possible Solutions
○	×	○	×	No station address received	Check the PLC program and the operation where the problem occurred.
○	×	×	□	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
○	×	×	×	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
×	○	○	□	A response was received after polling, but a CRC error occurred when the reflex data was checked.	Remove the source of electrical noise interference.
×	○	○	×	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues. • See if the master device is actually set to function as a remote device station.
×	○	×	□	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
×	○	×	×	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
×	×	○	□	CRC errors occurs when the station address is checked.	Remove the source of electrical noise interference.
×	×	○	×	• No station address • Cannot receive station address due to electrical noise interference	Remove the source of electrical noise interference.
×	×	×	□	Problem with the hardware	• Try cycling the power. Replace the CC-Link Option if the problem continues.
×	×	×	×	Data cannot be received (CC-Link communications cable may be disconnected)	Check the wiring.
×	×	*	○	The station address or communications speed is set incorrectly.	Enter the proper settings and cycle power.
○	○	○	□	The station address or communications speed was changed without cycling power afterwards.	• Return any incorrect settings to their original values and cycle power. • Enter the proper settings and cycle power.

Note:
• ○: ON / □: Flashing / ×: OFF / * : Either ON or OFF
• SD and RD may appear to flash with slower baud rates.

■ Faults when Running Multiple Drives

The example below demonstrates how to read the LED display on the front cover of the drive to determine the cause of a fault and the corrective action to take when multiple drives are running from the same network. The example assumes that SW, M/S, and PRM on the master device are all off, indicating that the master device is operating normally.

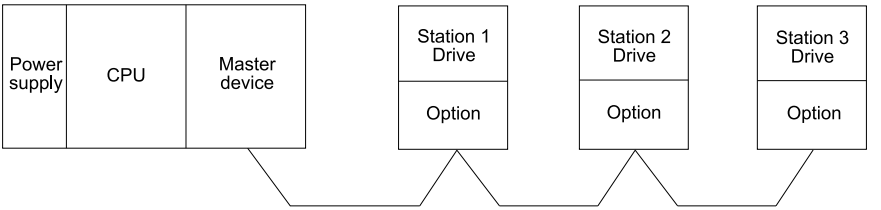


Figure 9.3 Connecting Multiple Drives on the Same Network

Table 9.3 LED Fault Display for CC-Link Option with Multiple Drives

LED Status				Cause	Possible Solutions
Master	Remote Device Addresses (Option)				
	Station 1	Station 2	Station 3		
	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	Normal operation	-
TIME LINE ○ TIME LINE ○	L.RUN × SD × RD × L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option for Station 1 is not correctly installed.	Make sure that the CC-Link Option and drive are connected together correctly.
or TIME LINE × TIME LINE ○	L.RUN * SD * RD * L.ERR *	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option for the first station is damaged. (most often all LEDs are out) **Note:** Sometimes an error will appear on the drive keypad.	Replace the CC-Link Option.
	L.RUN ○ SD ○	L.RUN × SD	L.RUN × SD *	Because L.RUN after Station 2 is OFF, either the communication line	Make sure that the components are connected correctly, using the LEDs

LED Status									Cause	Possible Solutions
Master	Remote Device Addresses (Option)									
	Station 1			Station 2			Station 3			
	RD	○		RD	★ ★		RD	*	between Station 1 and Station 2 is disconnected, or the connector is loose.	as a guide to indicate a correct connection.
	L.ERR	×		L.ERR	×		L.ERR	×		
	L.RUN	×		L.RUN	×		L.RUN	×	Communication cable has short-circuited.	Look for any short-circuits along the communication lines and fix any problems.
	SD	*		SD	*		SD	*		
	RD	*		RD	*		RD	*		
	L.ERR	×		L.ERR	×		L.ERR	×		
	L.RUN	×		L.RUN	×		L.RUN	×	Communication cable is not wired correctly.	Check the wiring for the CC-Link Option connector and fix any mistakes.
	SD	*		SD	*		SD	*		
	RD	*		RD	*		RD	*		
	L.ERR	*		L.ERR	*		L.ERR	*		
	L.RUN	×		L.RUN	○		L.RUN	×	Options for Station 1 and Station 3 are assigned the same address.	Enter the correct station address and cycle power.
	SD	*		SD	○		SD	*		
	RD	○		RD	○		RD	○		
	L.ERR	*		L.ERR	×		L.ERR	×		
	L.RUN	○		L.RUN	×		L.RUN	○	Option for Station 2 has a different communication speed setting than the master device.	Set the correct communication speed and cycle power.
	SD	○		SD	×		SD	○		
	RD	○		RD	○		RD	○		
	L.ERR	×		L.ERR	×		L.ERR	×		
	L.RUN	○		L.RUN	○		L.RUN	○	The settings for the Option connected to Station 3 were changed without cycling power.	• Return any incorrect settings to their original values and cycle power. • Enter the correct settings and cycle power.
	SD	○		SD	○		SD	○		
	RD	○		RD	○		RD	○		
	L.ERR	×		L.ERR	×		L.ERR	□		
	L.RUN	×		L.RUN	○		L.RUN	○	Parameters related to the Option (*F6-10 [CC-Link Node Address]*, *F6-11 [CC-Link Communication Speed]*) for Station 1 are set outside the acceptable range.	Set *F6-10* and *F6-11* correctly and cycle power.
	SD	×		SD	○		SD	○		
	RD	○		RD	○		RD	○		
	L.ERR	○		L.ERR	×		L.ERR	×		
TIME LINE × TIME LINE × or TIME LINE ○	L.RUN	○		L.RUN	○		L.RUN	○	The Option connected to Station 2 is experiencing electrical noise interference. (L.RUN is sometimes OFF)	Make sure that the options, drives, and master device are all grounded correctly.
	SD	○		SD	○		SD	○		
	RD	○		RD	○		RD	○		
	L.ERR	×		L.ERR	○		L.ERR	×		

LED Status				Cause	Possible Solutions
Master	Remote Device Addresses (Option)				
	Station 1	Station 2	Station 3		
TIME LINE ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ○	L.RUN ○ SD ○ RD ○ L.ERR ○	Electrical noise interference along the cable running between Station 2 and Station 3. (L.RUN is sometimes OFF)	Reconnect the communication line to the SLD terminal on the CC-Link Option connector. Also make sure that all power cables are properly separated from communication lines. (at least 100 mm away)
	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ○	Termination resistor not connected (L.RUN is sometimes OFF). (L.RUN is sometimes OFF)	Configure the final station in the series with a termination resistor.

Note:

○: ON / □: Flashing / ×: OFF / ✱ : Either ON or OFF

◆ Option Compatibility

You can connect a maximum of 3 options at the same time depending on the type of option.

Note:

- You can only connect one option to a GA500 drive. Connect the option to the CN5 connector.
- Compatible communication options are different for different models. Refer to the drive manuals for more information.

Table 9.4 Option Compatibility

Option	Connector	Number of Options Possible
PG-B3 *1*, PG-X3 *1*	CN5-B, C	2 *2*
PG-RT3 *1 *3 *4*, PG-F3 *1 *3 *4*	CN5-C	1
DO-A3 *1*, AO-A3 *1*	CN5-A, B, and C	1
SI-C3, SI-N3, SI-P3, SI-S3, SI-T3, SI-ET3, SI-ES3, SI-B3, SI-M3, SI-W3 *4*, SI-EM3 *4*, SI-EM3D *4*, SI-EN3 *4*, SI-EN3D *4*, SI-EP3, JOHB-SMP3, AI-A3 *1 *5*, DI-A3 *1 *5*	CN5-A	1

*1 Not available for GA500 drives.

*2 To connect two PG options, use the CN5-C and CN5-B connectors. To connect only one PG option, use the CN5-C connector.
*3 If you use the motor switching function, you cannot use this option.
*4 Not available for 1000-Series drive models with capacities between 450 and 630 kW (650 to 1000 HP).
*5 To use AI-A3 and DI-A3 input statuses as monitors, connect the options to CN5-A, CN5-B, or CN5-C.

10 European Standards

Figure 10.1 CE Mark

The CE mark indicates compliance with European safety and environmental regulations.

European standards include the Machinery Directive for machine manufacturers, the Low Voltage Directive for electronics manufacturers, and the EMC Directive for controlling noise.

It is required for engaging in business and commerce in Europe.

This option displays the CE mark based on the EMC guidelines.

EMC Directive: 2014/30/EU

Drives used in combination with this option and devices used in combination with the drive must also be CE certified and display the CE mark.

When using drives displaying the CE mark in combination with other devices, it is ultimately the responsibility of the user to ensure compliance with CE standards. Verify that conditions meet European standards after setting up the device.

◆ EMC Directive Compliance

This option is tested according to European standard EN 61800- 3:2004/A1:2012 and complies with the EMC Directive. The CE marking is declared based on the harmonized standards.

■ Option Installation

Verify the following installation conditions to make sure that other devices and machinery used with this option and drive also comply with EMC Directive:

1. Use dedicated shielded cable for the option and external device (for example, encoder, I/O device, or master), or route the wiring through a metal conduit.

2. Keep wiring as short as possible and ground the largest possible surface area of the shield to the metal panel as specified by Figure 10.3. Figure 10.2

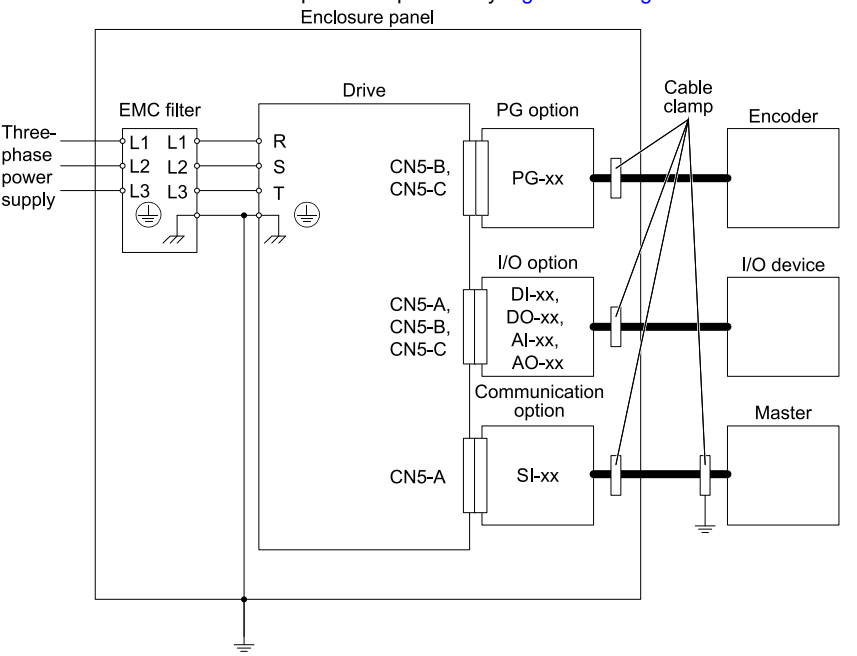


Figure 10.2 Option Installation for CE Compliance: 1000-Series, GA700, GA800

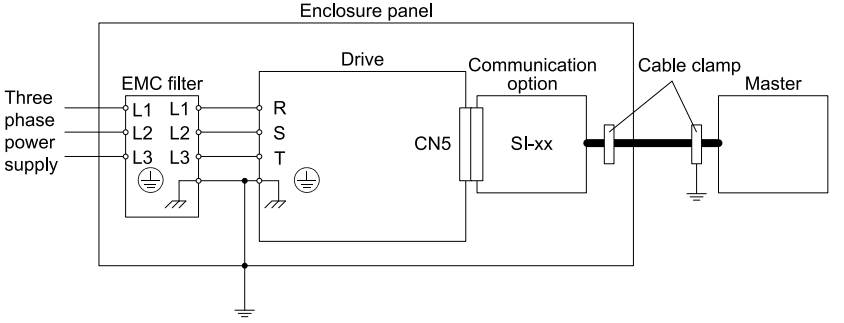
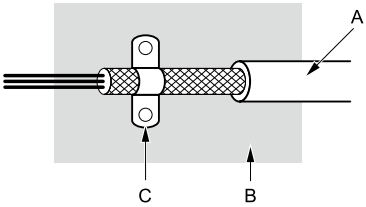


Figure 10.3 Option Installation for CE Compliance: GA500

3. Ground the largest possible surface area of the shield to the metal panel.
   Using cable clamps is recommended.



A - Braided shield cable
B - Metal panel
C - Cable clamp (conductive)

Figure 10.4 Ground Area

11 Precautions for Korean Radio Waves Act

Figure 11.1 KC Mark

This product confirms to broadcast and communications equipment for business use (Class A) and are designed for use in locations other than in ordinary houses.

Drives that bear the Korea Certification (KC) mark conform to the Korean Radio Waves Act. Be careful when you use the drive in Korea under the following conditions.

Table 11.1 Precaution When You Use this Drive

Precautions
This equipment is evaluated for compatibility for use in a business environment and may cause radio interference in a domestic environment.

Note:
The user guide applies only to “Business Broadcasting Communication Equipment”.

Comply with the EMC Directive to conform to the Korean Radio Act.

12 Specifications

◆ Specifications

Table 12.1 Option Specifications

Items	Specifications
Model	SI-C3
CC-Link Version	Complies with CC-Link Ver.1.10
Station Type	Remote device station
No. of Occupied Stations	1
Communication Speed	156 kbps to 10 Mbps
Ambient Temperature	-10 °C - +50 °C (14 °F - 122 °F)
Humidity	Up to 95% RH (no condensation)
Storage Temperature	-20 °C - +60 °C (-4 °F - 140 °F) allowed for short-term transport of the product
Area of Use	Indoors and free from: • Oil mist, corrosive gas, flammable gas, and dust • Radioactive materials or flammable materials, including wood • Harmful gas or fluids • Salt • Direct sunlight • Falling foreign objects
Altitude	Up to 1000 m (3280 ft)

Note:

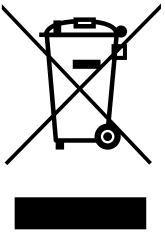
The number of drives that can be connected to the network varies depending on the type of nodes connected. Refer to *Related Drive Parameters on page 34* for more information.

13 Disposal

◆ Disposal Instructions

Correctly dispose of the product and packing material as specified by applicable regional, local, and municipal laws and regulations.

◆ WEEE Directive



The wheelie bin symbol on this product, its manual, or its packaging identifies that you must recycle it at the end of its product life.

You must discard the product at an applicable collection point for electrical and electronic equipment (EEE). Do not discard the product with usual waste.

Revision History

Date of Publication	Revision Number	Section	Revised Content
February 2026	1	Back cover	Revision: Address
September 2022	-	-	First Edition This manual is created base on TOBP C730600 83D<7>-0.

YASKAWA AC Drive Option

CC-Link
Installation Manual

DRIVE CENTER (INVERTER PLANT)
2-13-1, Nishimiyaichi, Yukuhashi, Fukuoka,
824-8511, Japan
Phone: +81-930-25-2548 Fax: +81-930-25-3431
www.yaskawa.co.jp

YASKAWA ELECTRIC CORPORATION
New Pier Takeshiba South Tower, 1-16-1, Kaigan,
Minatoku, Tokyo, 105-6891, Japan
Phone: +81-3-5402-4502 Fax: +81-3-5402-4580
www.yaskawa.co.jp

YASKAWA AMERICA, INC.
2121, Norman Drive South, Waukegan, IL 60085, U.S.A.
Phone: +1-800-YASKAWA (927-5292) or +1-847-887-7000
Fax: +1-847-887-7310
www.yaskawa.com

YASKAWA ELÉTRICO DO BRASIL LTDA.
777, Avenida Piraporinha, Diadema, São Paulo,
09950-000, Brasil
Phone: +55-11-3585-1100 Fax: +55-11-3585-1187
www.yaskawa.com.br

YASKAWA EUROPE GmbH
Philipp-Reis-Str. 6, 65795 Hattersheim am Main, Germany
Phone: +49-6196-569-300
www.yaskawa.eu.com
E-mail: support@yaskawa.eu

YASKAWA ELECTRIC KOREA CORPORATION
6F, 112, LS-ro, Dongan-gu, Anyang-si, Gyeonggi-do, Korea
Phone: +82-31-8015-4224 Fax: +82-31-8015-5034
www.yaskawa.co.kr

YASKAWA ASIA PACIFIC PTE. LTD.
30A, Kallang Place, #06-01, 339213, Singapore
Phone: +65-6282-3003 Fax: +65-6289-3003
www.yaskawa.com.sg

YASKAWA ELECTRIC (THAILAND) CO., LTD.
59, 1F-5F, Flourish Building, Soi Ratchadapisek 18,
Ratchadapisek Road, Huaykwang, Bangkok, 10310,
Thailand
Phone: +66-2-017-0099 Fax: +66-2-017-0799
www.yaskawa.co.th

YASKAWA ELECTRIC (CHINA) CO., LTD.
22F, Link Square 1, No.222, Hubin Road, Shanghai,
200021, China
Phone: +86-21-5385-2200 Fax: +86-21-5385-3299
www.yaskawa.com.cn

YASKAWA ELECTRIC (CHINA) CO., LTD.
BEIJING OFFICE
Room 1011, Tower W3 Oriental Plaza, No. 1,
East Chang An Avenue,
Dong Cheng District, Beijing, 100738, China
Phone: +86-10-8518-4086 Fax: +86-10-8518-4082

YASKAWA ELECTRIC TAIWAN CORPORATION
12F, No. 207, Section 3, Beishin Road, Shindian District,
New Taipei City 23143, Taiwan
Phone: +886-2-8913-1333
Fax: +886-2-8913-1513 or +886-2-8913-1519
www.yaskawa.com.tw

YASKAWA INDIA PRIVATE LIMITED
#17/A, Electronics City, Hosur Road, Bengaluru,
560 100 (Karnataka), India
Phone: +91-80-4244-1900 Fax: +91-80-4244-1901
www.yaskawaindia.in

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In the event that the end user of this product is to be the military and said product is to be employed in any weapons systems or the manufacture thereof, the export will fall under the relevant regulations as stipulated in the Foreign Exchange and Foreign Trade Act. Therefore, be sure to follow all procedures and submit all relevant documentation according to any and all rules, regulations and laws that may apply.

Specifications are subject to change without notice for ongoing product modifications and improvements.

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TOEPC730600083

MANUAL NO. TOEP C730600 83A <1>-0
Published in Japan February 2026
25-9-27
Original Instructions